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Design and Simulation of Short Channel Si:HfO₂ Ferroelectric Field Effect Transistor (FeFET)

By

Idris H. Smaili

A Thesis Submitted in Partial Fulfillment of the Requirements for the Degree of Master of Science in Microelectronic Engineering

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Idris H. Smaili

Date

Dedication

I dedicate this thesis to my family: my father, my mother, my wife and my sons. Without your encouragement and support this work would not have been possible.

Acknowledgements

I would like to thank my advisor Dr. Santosh Kurinec for her support and guidance over the past years. Dr. Kurinec's encouragement and insistence on student involvement and collaboration with academic and industrial research has opened many doors. I would also like to thank Dr. Robert Pearson, Dr. Karl Hirschman and Dr. Ivan Puchades, my thesis committee members for their assistance and continuing support.

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I gratefully acknowledge the academic donation of Silvaco TCAD tools by Silvaco used in this study.

Abstract

Non-volatile memories using ferroelectric capacitors, known as Ferroelectric Random Access Memory (FRAM) have been studied for many years, but they suffer from loss of data during read out process. Ferroelectric Field Effect Transistors (FeFETs), which are based on ferroelectric gate oxide, have been of recent interest for non-volatile memory applications. The FeFETs utilize the polarization of the ferroelectric layer incorporated into the transistor gate stack to control the channel conductivity. Therefore, in FeFET devices, the read out process is non-destructive because it is only processed by measuring the resistivity in the channel region. The drain current-gate voltage (I_D-V_G) characteristics of FeFETs exhibit a voltage shift due to polarization hysteresis known as the "memory window", an important figure of merit of a FeFET that provides a window for the read voltage. A dielectric layer between semiconductor layer and the ferroelectric is required to reduce charge injection effect, and to compensate lattice mismatch between the ferroelectric and the semiconductor. In addition, a non-ferroelectric interfacial layer may form between the semiconductor and the ferroelectric layer. However, this dielectric layer causes a voltage drop since the system becomes equivalent to two serial capacitors. It also causes an electric field that opposes the polarization. Using a high permittivity material such as HfO₂ reduces the voltage drop and the effect of depolarization.

To date, the majority of the work involving FeFETs has been based on conventional ferroelectric materials such as Lead Zirconate Titanate (PZT) and Strontium Bismuth Tantalate (SBT). These materials are not compatible with standard IC processing and furthermore scaling thicknesses in PZT and SBT result in loss of polarization

characteristics. Recently, ferroelectricity has been reported in doped hafnium oxide thin films with dopants such as Si, Al, and Gd. Particularly, silicon doped hafnium oxide (Si:HfO₂) has shown promise. In this material, the remnant polarization considerably increases by decreasing the layer thickness. The lower permittivity of Si:HfO₂ compared to that of PZT and SBT, allows to employ thinner films that reduce fringing effects.

This study focuses on employing $Si:HfO_2$ in short channel FeFETs. The study has two major objectives. First, to show that short channel FeFETs can be accomplished with large memory window. Second, to demonstrate the role of bulk layer thickness and permittivity on FeFET performance.

N-channel metal oxide semiconductor FET (N-MOSFET) with printed channel length of 26 nm has been designed with Si:HfO₂ as the ferroelectric layer, and TiN as the gate electrode. The effects of buffer layer thickness and permittivity and ferroelectric layer thickness on the memory window have been explored using Silvaco Atlas software that employs ferroelectric FET device physics developed by Miller et al. Polarization characteristics reported for Si:HfO₂ have been incorporated in this model. The simulations performed in this study have shown that using Si:HfO₂ as a ferroelectric material makes it possible to accomplish short channel FeFETs with good performance even without using buffer layers. This means it is possible to minimize depolarization effects. Using Si:HfO₂ as a ferroelectric layer makes it possible to accomplish highly scaled and ultra-low-power FeFETs.

Table of Contents

Title Page	i
Dedication	iii
Acknowledgements	iv
Abstract	v
Table of Contents	vii
List of Figures	ix
List of Tables	xiv
List of Symbols	Xv
List of Acronyms	xvii
Chapter 1: Introduction	1
1.1 Introduction and Motivation	1
1.2 Scaling Theory	3
1.3 Focus of this Study	4
Chapter 2: Background Information	5
2.1 Ferroelectric Materials	5
2.2 Ferroelectric Capacitor	10
2.3 Ferroelectric Field Effect Transistor (FeFET)	12
2.4 Electrostatics of Metal-Insulator-Ferroelectric-Semiconductor (MFIS)	13
FeFET	
2.5 Current-voltage characteristics	19

2.6 Depolarization, Trapping and Charge Injection Effects	21
2.7 Evolution of FeFETs on Conventional Perovskites	27
2.8 Limitations of PZT and SBT for FeFET Applications	31
2.9 Ferroelectricity in Silicon Doped Hafnium Oxide (Si:HfO ₂)	32
2.10 Research Objectives	36
Chapter 3: Silvaco Atlas Simulations Methodology	37
3.1 Silvaco	37
3.2 Silvaco Atlas	40
3.3 The Ferroelectric Permittivity Model in Atlas	42
3.4 Methodology specifications	44
Chapter 4: Results and Analysis	47
4.1 Device Parameters (n-FeFET Parameters)	47
4.2 Effect of the Ferroelectric Layer Thickness	49
4.3 Effect of Buffer Layer Thickness	51
4.4 Effect of Buffer Layer Permittivity	53
4.5 Effect of Applied Electric Field	55
4.6 Effect of Polarization on Threshold Voltage	56
Chapter 5: Conclusions and Future Work	59
5.1 Conclusions	59
5.2 Future Work	60
References	62
Appendix A Appendix B Appendix C	A B J

List of Figures

Fig.	Description	Page
1.1	(a) ABO ₃ perovskite unit cell	1
	(b) Polarization – Electric field hysteresis	1
1.2	Ferroelectric base semiconductor devices	2
2.1	States of middle atom in BaTiO ₃ (a) up polarization	6
	States of middle atom in BaTiO ₃ (b) down polarization	6
2.2	Ferroelectric domains concept	6
2.3	Typical curve of polarization hysteresis loop	7
2.4	The crystal structure of PZT showing movement of Ti/Zr ion that	8
	result in two states of polarization for temperatures below the Curie	
	temperature	
2.5	Crystal structure of -layered perovskite SrBi ₂ Ta ₂ O ₉ (SBT) showing	9
	an upper half of the unit cell)	
2.6	Polarization hysteresis loops of PZT and SBT ferroelectric thin films	9
2.7	Polarization states of a ferroelectric capacitor	10
2.8	(a) Cross section of a 1T-1C cell structure	10
	(b) basic memory unit cell array	10
2.9	FeRAM read cycle	11
2.10	(a) Main structure of FeFET	12
	(b) 1T type memory cell	12
2.11	Schematic of programming a FeFET. (a) The device is in off-state	13

with its polarization in negative direction

	Schematic of programming a FeFET. (b) application of a pulse that	13
	drives it to saturation (P_s) and retained at its remnant value (P_r)	
2.12	Schematic of reading a FeFET. The read voltage lies in the	13
	'memory window' of the FeFET	
2.13	Schematic of a MFIS FeFET	14
2.14	C-V curves of a metal-ferroelectric-insulator-semiconductor	18
	capacitor	
2.15	A MOSFET and a ferroelectric capacitor characteristics combine to	20
	give the FeFET I-V characteristics. The dashed curve represents an	
	ideal ferroelectric	
2.16	Simulated I-V sub-loops in the I_{DS} -V _G characteristics for the	20
	parameters shown	
2.17	Reading performed by applying a read voltage somewhere in	21
	memory window: where I_{on}/I_{off} ratio is high; (a) for Flash	
	Reading performed by applying a read voltage somewhere in	21
	memory window: where I_{on}/I_{off} ratio is high (b) for FeFET	
2.18	Model of a MFIS ferroelectric capacitor with a depolarization field	22
2.19	A schematic capacitance design of the MFIS structure	23
2.20	Gate leakage effects in MFIS FeFET devices (a) Inverted	25
	semiconductor immediately after polarization	
	Gate leakage effects in MFIS FeFET devices (b) depolarization after	26

time

2.21	Various charge transport mechanisms in insulators	26
2.22	C-V characteristics of Al/SBT (280 nm)/HfO ₂ /Si (a) with 3 nm	27
	HfO2 buffer layer	
	C-V characteristics of Al/SBT (280 nm)/HfO ₂ /Si (b) with 12 nm	27
	buffer layer	
	C-V characteristics of Al/SBT (280 nm)/HfO ₂ /Si (c) with 18 nm	27
	buffer layer	
2.23	I-V characteristics of the PZT-based FeFET using ITO/PZT/SRO/Pt	28
	structure	
2.24	Measured hysteresis loops of ferroelectric films with different	28
	niobium doping levels	
2.25	Effect of voltage divider due to using a buffer layer	29
2.26	I_d - V_d characteristics of the FeFET with (a) SiO ₂	30
	I_d - V_d characteristics of the FeFET with (b) Y_2O_3 dielectric layers	30
2.27	C-V characteristics of FeFET with HfO_2 and SiO_2 dielectrics	30
2.28	Fringing effects due to thicker gate dielectric	31
2.29	Polarization hysteresis loop of the simulated FeFET	33
2.30	Improved polarization by doping HfO_2 with 4.4 mol. % SiO_2	33
2.31	The experimental verification of TCAD simulations	34
2.32	The I_d - V_g curves of the simulated FeFET device (a) with 10 nm	35
	thick ferroelectric layer	
	The I_d - V_g curves of the simulated FeFET device (b) with 30 nm	35

thick ferroelectric layer

2.33	Structure of the QMFeFET (a) with buffer layer 3	
	Structure of the QMFeFET (b) without buffer layer	35
3.1	Silvaco main modules	37
3.2	Inputs and outputs of Silvaco Atlas	40
4.1	Main structure of the simulated FeFET	49
4.2	Simulated FeFET device (a) with 15 nm	50
	Simulated FeFET device (b) with 12 nm	50
	Simulated FeFET device (c) with 10 nm	50
	Simulated FeFET device (d) with 8 nm thick ferroelectric layer	50
4.3	Effect of ferroelectric layer thickness	50
4.4	FeFET device (a) with 8 Å thick HfO ₂ buffer layer	52
	FeFET device (b) with 5 Å thick HfO_2 buffer layer	52
	FeFET device (c) without buffer layer	52
4.5	I-V hysteresis loops of the FeFET device with 8 Å thick HfO_2 buffer	52
	layer, with 5 Å thick HfO_2 buffer layer and without buffer layer	
4.6	FeFET device with 8 Å of (a) HfO_2 buffer layer	54
	FeFET device with 8 Å of (b) SiO_2 buffer layer	54
	FeFET device with 8 Å of (c) Si_3N_4 buffer layer	54
4.7	I-V hysteresis loops of the FeFET device with 8 Å of HfO_2 buffer	55
	layer, SiO_2 buffer layer, and Si_3N_4 buffer layer	
4.8	I-V hysteresis loops of the FeFET device with different applied	56
	electric fields	

4.9	Transistor device with no ferroelectric layer	57
4.10	I-V curve of the transistor with no ferroelectric layer	57
5.1	Suggested subjects for future work	61

List of Tables

Table	Description	Page
1.1	Main scaling rules of MOSFETs	3
3.1	Input specification of Silvaco Atlas	41
3.2	Default values and units of ferroelectric parameters	43
4.1	Parameters of the simulated device	47
4.2	Permittivity characteristics of the Si:HfO ₂ ferroelectric material	48
	for different thicknesses and the calculated maximum memory	
	window values	
4.3	Comparison of results of the simulated devices	51
4.4	Effect of buffer layer thickness on the FeFET performance	53
4.5	Effect of buffer layer permittivity on the FeFET performance	55

List of Symbols

- P_s Spontaneous polarization
- P_r Remnant polarization
- E_c Coercive field
- V_g Gate voltage
- I_d Drain Current
- Φ Electric potential
- E Electric field
- ρ Charge density
- ε Semiconductor permittivity
- q Electron charge
- p Holes
- n Electrons
- N_d⁺ Charge density of ionized donors
- N_a Charge density of ionized acceptors
- μ_p Hole mobility
- D_p Hole diffusivity
- μ_n Electron mobility
- D_n Electron diffusivity
- D Diffusion coefficient
- μ Mobility

Gn

- G_p Generation rate of excess holes
 - Generation rate of excess electrons
- R_p Recombination rate of holes

- R_n Recombination rates of electrons
- J_p Current density of holes
- J_n Current density of electrons
- *P*_d Position dependent dipole polarization
- *P_{sat}* Saturated loop polarization
- **Γ** Unity function
- ξ Polarization direction

List of Acronyms

FeFET	Ferroelectric Field Effect Transistor	
Si:HfO ₂	Silicon doped hafnium oxide	
SCE	Short Channel effects	
PZT	Lead Zirconate Titanate	
SBT	Strontium Bismuth Tantalate	
MFS	Metal Ferroelectric semiconductor	
MFIS	Metal Ferroelectric Insulator	
	Semiconductor	
MSM	Metal Ferroelectric Metal	
MFMIS	Metal Ferroelectric Metal Insulator	
	Semiconductor	
QMFeFET	Quantum Metal FeFET	
ITRS	International Technology Roadmap for	
	Semiconductors	
VWF	Virtual Wafer Fab	
MW	Memory Window	
NCFET	Negative Capacitance FET	
FTJ	Ferroelectric Tunnel Junction	

CHAPTER 1 - INTRODUCTION

This chapter gives an introduction to ferroelectric materials and their applications to achieve non-volatile memories. It subsequently develops the primary focus of the study in this thesis.

1.1 Introduction and Motivation:

Ferroelectricity is a property of certain materials in which they possess a spontaneous electric polarization that can be reversed by the application of an external electric field. Ferroelectric materials were discovered during studies of Rochelle salt. These materials have the ability to show reversible and spontaneous polarization even when there is no electric field and are characterized by a characteristic polarization hysteresis loop. Above the Curie temperature of a ferroelectric material, it can be polarized under an electric field, i.e. paraelectric material. This is because of the change in the structure at this transition temperature. On the other hand, ferroelectric materials show spontaneous polarization below the Curie temperature.



Fig. 1.1. (a) ABO₃ perovskite unit cell; (b) Polarization – Electric field hysteresis [1].

This occurs as a result of the displacement of the central ion in a crystal unit cell as seen in Fig. 1.1 [2]-[4]. The main advantage of ferroelectric materials is their ability to maintain a memory state. The hysteresis of polarization with electric field is the key to memory applications.

It has been a growing trend in modern times to develop ferroelectric memories that can keep data without changing state. The main advantage of integrating ferroelectric materials with FETs is that the reading process is a non-destructive process. Fig. 2.1 shows the landscape of ferroelectric-based semiconductor devices.



Fig. 1.2. Ferroelectric based semiconductor devices.

FeRAM is a ferroelectric capacitor that is combined with a MOSFET in a random access memory circuit. These types of devices suffer from loss of data during the readout process. Therefore, it was necessary to find a new approach in order to keep data without change. In FeFET devices, the typical ferroelectric capacitor is replaced with a ferroelectric –gate field effect transistor. FeFET devices depend on the resistance between source and drain during the reading process to indicate the data state of "0" or "1". Thus, it is possible to avoid data loss [5].

1.2 Scaling Theory:

The scaling of CMOS devices in microelectronics is driven by the performance metrics and the integration density. Several rules of scaling have been proposed to study the effect of size reduction. The first rules were introduced by R. H. Dennard (1974) as seen in Table 1.1.

Device Parameter	Scaling Factor
Dimensions (L, W, X _{ox} and X _j)	1/K
Area	$1/K^2$
Packing Density	K^2
Bias Voltage and V _t	1/K
Bias Currents	1/K
Power Dissipation	$1/K^2$
Capacitance	$1/K^2$
Electric Field Intensity	1
Body Effect Coefficient	$1/K^{0.5}$
Transistor Transit time	1/K
Transistor Power Delay Product	$1/K^3$

Table 1.1: Main scaling rules of MOSFETs [6]

Where K is the scaling factor and it can be calculated as following:

$$K = \frac{Old \text{ Size}}{New \text{ Size}}$$
(1.1)

Since the ultimate limit for the scaling is determined by physical parameters, the scaling rules in Table 1.1 do not show limits for the MOSFETs scaling.

1.3 Focus of this Study:

This work studies designing and simulation of a short channel Si:HfO₂ Ferroelectric Field Effect Transistor (Si:HfO₂ FeFET). The proposed device is mainly based on ferroelectric gate oxide.

Silvaco Atlas has been used to simulate this device and to study the polarization and hysteresis characteristics. FeFETs are novel and promising devices since they provide fast and non-volatile memories, which would be a major technological advance. A short channel device has been chosen to be studied in order to match the International Technology Roadmap for Semiconductors (ITRS). This device has been simulated with silicon doped hafnium oxide (Si:HfO₂) as a ferroelectric layer. The polarization characteristics of this material have been studied with short channel FeFETs. This is important because the ferroelectric material can significantly affect the FeFET performance.

The main goal of this work is to accomplish short channel FeFETs that have large memory windows by using Si:HfO₂ as a ferroelectric layer. The second goal of this work is to investigate the role of using a buffer layer with Si:HfO₂ as a ferroelectric material.

CHAPTER 2 - BACKGROUND INFORMATION

This chapter focuses on ferroelectric materials and their applications. It provides additional details beyond what was described in Chapter 1. Section 2.1 discusses the properties of ferroelectric materials. Section 2.2 explains the basics of FeRAM device and its limitations. Section 2.3 describes the concept of FeFETs and the advantages of these kinds of devices. Section 2.4 covers the electrostatics of Metal-Insulator-Ferroelectric-Semiconductor (MFIS) FeFETs. Sections 2.5 discusses the current-voltage characteristics of FeFETs. Section 2.6 explains the depolarization, charge injection and trapping effects. Section 2.7 covers the evolution of FeFET devices on conventional perovskite materials. Section 2.8 discusses the limitations of PbZn_{1-x}Ti_xO₃ (PZT) and SrBi₂Ta₂O₉ (SBT) ferroelectric materials. Section 2.9 gives a literature review about ferroelectricity in silicon doped hafnium oxide (Si:HfO₂).

2.1 Ferroelectric Materials:

Most Ferroelectric materials have perovskite crystalline structure. The perovskite structure has the general stoichiometry ABO₃, where "A" and "B" are cations and "O" is an anion. The atom in the middle has two stable low energy levels as seen in Fig. 2.1. When an electric field is applied, the middle atom moves in the same direction as that of the electric field resulting in polarization. The two states of the middle atom are typically classified as up polarization and down polarization according to the position of the atom. Fig. 2.1 shows the two states of the middle atom in a perovskite barium titanate (BaTiO₃) ferroelectric material.



Fig. 2.1. States of middle atom in BaTiO₃ (a) up polarization (b) down polarization [7].

Ferroelectric materials typically show spontaneous polarization, which means that the ferroelectric material is able to get polarized even when the applied electric field is equal to zero. This property is known as ferroelectricity, which is caused by the presence of permanent dipole moment. In ferroelectric materials, there are certain regions, i.e. domains, where in all dipoles are pointed in certain directions. When there is no applied electric field, the net polarization is equal to zero due to random orientations of domains as seen in Fig. 2.2(a). When an external electric field is applied, dipole moments rotate to align themselves along the electric field forming a bigger region that has a net dipole moment oriented in a single direction as seen in Fig. 2.2(b) [5]



Fig. 2.2. Ferroelectric domains concept.

These created domains do not disappear when the electric field is removed. The hysteresis effect results by these irreversible polarization processes as shown in Fig. 2.3. Small displacements that occur in weak electrical fields are reversible. Remnant polarization (P_r) refers to the polarization value when there is no applied electric field.



 P_s : Spontaneous Polarization P_r : Remanent Polarization E_c : Coercive Field

Fig. 2.3. Typical curve of polarization hysteresis loop [1].

The strength of the electric field that is needed to bring back the polarization to zero is known as coercive field (E_c). To switch the state of a ferroelectric device, the threshold electric field should be greater than the coercive field (E_c). If the electric field is applied in the same direction of the previous applied electric field, no switching will take place and the charge will still be the same [5].

Shur, Makarov and Volegov (1995) developed a method to estimate domain kinetics of ferroelectric materials. In their results, they found that it is possible to estimate domain kinetics in real devices and to produce devices with controlled domain structure. It is important to understand that domain kinetics differ with regard to the type of ferroelectric material which can significantly affect the device performance [8]. Two most widely studied ferroelectric materials are $PbZn_{1-x}Ti_xO_3$ (PZT) and $SrBi_2Ta_2O_9$ (SBT). They both have perovskite structure. PZT is a more classic type of ferroelectric whereas SBT is a layered perovskite. In PZT, the zirconium and titanium in the lattice have two stabilization points. They can move between the points according to the external electric field resulting in polarization. An electric polarization of PZT (shift up/down of Zr/Ti atom) remains after applying and removing an external electric field, from which a nonvolatile property results. Typically, ferroelectric materials show ferroelectricity below a certain transition temperature, which is also known as the Curie temperature. PZT is an intermetallic inorganic compound that shows a marked piezoelectric effect. PZT material shows larger spontaneous polarization and it has a high polarization coefficients. Its transition temperature is about 370 °C. The properties of PZT depend on the composition of the alloy. Currently, high switchable polarization and clearly defined switching are offered by employing Ti/Zr ratios of 60/40 and 70/30 [5]. Fig. 2.4 shows the crystal structure of PZT material.



Fig. 2.4. The crystal structure of PZT showing movement of Ti/Zr ion that result in two states of polarization for temperatures below the Curie temperature [9].

In the layered perovskite structure of the SBT, the perovskite unit cells (SrTaO) are interrupted with bismuth oxide layers. Refer to Fig. 2.5 for the structure of SBT where a

half unit cell is displayed [10]. SBT material has few allowed directions of spontaneous polarization and it has a lower remnant polarization. Its transition temperature is about 570 °C. The advantage of this material is that it does not show polarization fatigue like PZT due to repeated switching process [5].



Fig. 2.5. Crystal structure of -layered perovskite SrBi₂Ta₂O₉ (SBT) showing an upper half of the unit cell) [10].

In principle, any of the above mentioned materials is suitable for the ferroelectric memory operation and is being considered for applications in the ferroelectric field effect transistors (FeFETs) too. The two materials differ in the polarization and coercive field values. Table in Fig. 2.6 shows the parameters of these two materials. Fig. 2.6 shows a comparison of polarization behavior of these two ferroelectric materials.



8

10

30

Fig. 2.6. Polarization hysteresis loops of PZT and SBT ferroelectric thin films [11].

2.2 Ferroelectric Capacitor:

A Ferroelectric capacitor is a device consisting of ferroelectric film between two electrodes. Since there are two states within ferroelectric materials, a proper electric field can be applied to polarize the capacitor either up or down as shown in Fig. 2.7.



Fig. 2.7. Polarization states of a ferroelectric capacitor [7].

Ferroelectric capacitor can be considered as the first generation of non-volatile ferroelectric memories and it is typically addressed by using a conventional field effect transistor forming 1T-1C cell configuration as shown in Fig. 2.8 [12].

Fig. 2.8 (a) Cross section of a 1T-1C cell structure; (b) basic memory unit cell array [13]

The capacitance of the ferroelectric capacitor is not stable. When the capacitor is not switched, it behaves in the normal linear fashion. When it is switched, an increase in the capacitance will induce an additional charge. In a memory cell, this effect can be enabled by using an active element, i.e. a field effect transistor (FET). The individual cell can be accessed by a word line and a bit line as seen in Fig. 2.8 (b).

The read operation requires a number of stages. The bit line voltage is compared to a reference, which is set to be below the switch voltage and above the un-switch voltage. A sense amplifier is typically used to amplify the difference giving either logic "0" or logic "1". When the bit line, plate line and the word line are low, the cell will be in its inactive state as shown in Fig. 2.9 (a).

Fig. 2.9. FeRAM read cycle [7].

When a voltage is applied onto the word line and plate line, the access operation starts as illustrated in Fig. 2.9 (b). When a voltage is applied across the capacitor, it will either switch or not switch. When the capacitor is switched, a charge, which is shared with the bit line capacitance (C_{bit}), is induced as shown in Fig. 2.9 (c). The voltage on the bit line is given by:

$$V_{bit} = \frac{C_s}{C_{bit}} V_{dd}$$
(2.1)

Where, C_s is the capacitance of the switched ferroelectric capacitor. No additional charge is induced when the capacitor does not switch. Thus, the data within the cell can be changed during the read process. The writing process uses the same principles of the read operation. An electric field is applied in the required direction by the control circuitry to write the desired data [7].

2.3 Ferroelectric Field Effect Transistor (FeFET):

In a FeFET, the gate oxide of a typical MOSFET is replaced by a ferroelectric material or a stack of materials with a ferroelectric layer as shown in Fig. 2.10.

Fig. 2.10. (a) Main structure of FeFET; (b) 1T type memory cell [13].

The FeFET is programmed by applying a pulse to switch its polarization to "on" state that is written by its remnant polarization as shown in Fig.2.11. The off-state is written by applying a negative pulse. The read operation is carried out by applying a read voltage at the gate that senses the channel conductivity between the source and the drain as seen in Fig. 2.12.

Fig. 2.11. Schematic of programming a FeFET. (a) The device is in off-state with its polarization in negative direction; (b) application of a pulse that drives it to saturation (P_s) and retained at its remnant value (P_r) .

Channel under depletion (high resistance)

Channel under inversion (low resistance)

Fig. 2.12. Schematic of reading a FeFET. The read voltage lies in the 'memory window' of the FeFET.

.2.4 Electrostatics of Metal-Insulator-Ferroelectric-Semiconductor (MFIS) FeFET:

Typically, an insulating interfacial layer exists between the ferroelectric layer and the semiconductor either intentionally to overcome stresses, to minimize charge injection or

to reduce interfacial reaction between the adjacent materials making it an MFIS device as seen in Fig. 2.13.

Fig. 2.13. Schematic of a MFIS FeFET.

For an MFIS-FeFET, shown in Fig. 2.13, the gate voltage is given as following [14]:

$$V_{G} = V_{FB} + V_{f} + V_{b} + \Psi_{s}$$

$$(2.2)$$

Where V_f is the voltage dropping in the ferroelectric layer, V_b is the voltage dropping in the insulator (buffer layer), and Ψ_s is the surface potential of the semiconductor. The electric displacements can be expressed as following:

$$\mathbf{D}_k = \varepsilon_k E_k + P_k \tag{2.3}$$

Where

$$\mathbf{k} = \left\{ f, b, s \right\} \tag{2.4}$$

Where *f*, *b* and *s* refer to ferroelectric layer, insulator layer (buffer layer) and semiconductor layer, respectively. ε_k is the permittivity, E_k is the electric field and P_k represents the polarization. According to the Gauss's law:

$$\varepsilon_s E_s = Q_s(\Psi_s) \tag{2.5}$$

Where $Q_s(\Psi_s)$ is the space charge/area in the semiconductor. Thus, equation 2.3 can be rewritten as following [15]:

$$Q_{s}(\Psi_{s}) = P\left(\frac{V_{f}}{t_{f}}\right)$$

$$Q_{s}(\Psi_{s}) = \frac{\varepsilon_{b}}{V_{b}}$$

$$(2.6)$$

$$(2.7)$$

 $Q_s(\Psi_s) = \frac{c_b}{t_b} V_b \tag{2.7}$

The semiconductor charge density for a p-type substrate can be expressed as:

$$Q_{s}(\Psi_{s}) = \Psi_{s} \times \frac{\sqrt{2}\varepsilon_{s}}{\beta L_{D}} \left(\frac{n_{i}^{2}}{N_{A}^{2}} \left(e^{-\beta\Psi_{s}} + \beta\Psi_{s} - 1 \right) + \left(e^{\beta\Psi_{s}} - \beta\Psi_{s} - 1 \right) \right)^{1/2}$$
(2.8)

Where,

$$L_D = \sqrt{\frac{\varepsilon_s}{qN_A\beta}}$$
(2.9)

$$\beta = \frac{q}{kT} \tag{2.10}$$

 L_D is the Debye length, N_A refers to the majority carrier concentration, n_i is the intrinsic carrier concentration, k is the Boltzmann constant and Q_s represents the semiconductor surface charge.

$$Q_G + Q_b + Q_s = 0 \tag{2.11}$$

$$V_f = \frac{Q_G - P}{C_f} \tag{2.12}$$

$$V_b = \frac{Q_G}{C_b} \tag{2.13}$$

Where, V_f is the voltage dropping in the ferroelectric layer and V_b is the voltage dropping in the buffer layer. Introducing effective gate voltage :

$$V_{G,eff} = V_G + \frac{P}{C_f}$$
(2.14)

And stack capacitance/area;

$$C_{stack} = \left(\frac{1}{C_f} + \frac{1}{C_b}\right)^{-1} = \left(\frac{t_f}{\varepsilon_0 \varepsilon_{rf}} + \frac{t_b}{\varepsilon_0 \varepsilon_{rb}}\right)^{-1}$$
(2.15)

$$\mathbf{V}_{G,eff} = V_G + \frac{P}{C_f} = \mathbf{V}_{FB} + \psi_s + \frac{Q_G}{C_{stack}}$$
(2.16)

Assume $Q_i = 0$ (no interface charge) $\Rightarrow Q_G = -Q_s$

$$\mathbf{V}_{G,eff} = \mathbf{V}_{FB} + \psi_s - \frac{Q_s}{C_{stack}}$$
(2.17)

$$\mathbf{V}_{G,eff} = \mathbf{V}_{FB} + \psi_s \pm \gamma \left[\left(\frac{kT}{q} e^{-\frac{q\psi_s}{kT}} + \psi_s - \frac{kT}{q} \right) + e^{-\frac{2q\phi_F}{kT}} \left(\frac{kT}{q} e^{\frac{q\psi_s}{kT}} - \psi_s - \frac{kT}{q} \right) \right]^{1/2}$$
(2.18)

where γ is now defined as :

$$\gamma = \frac{\sqrt{2q\varepsilon_s N_a}}{C_{stack}}$$
(2.19)

Where C_s is the semiconductor capacitance, C_f is the ferroelectric capacitance and C_b is the buffer layer capacitance.

In a typical P-E hysteresis loop, as the field is ramped between large absolute values opposite in sign, the switching dipole polarization P approaches asymptotic value of $\pm P_{s}$, where P_{s} is the spontaneous polarization, when all the dipoles are aligned, the resulting polarization is referred to as the saturation polarization. The polarization has a zero value

at a value of the electric field E_c . At zero field, the value of polarization is P_r , the remnant polarization. This is expressed as:

$$P^{+}(E) = -P^{-}(-E) \tag{2.20}$$

Where the plus (+) sign indicates the branch of the polarization for the positive going field ramp and the minus (-) sign indicates the negative going ramp. Various mathematical functions have been proposed to describe the hysteresis loop. The hyperbolic tangent function is chosen due to its convenient mathematical properties.

$$P^{+}(E) = P_{s} \tanh\left(\frac{E - E_{c}}{2\delta}\right)$$
(2.21)

Where,

$$\delta = E_c \left[\ln \left(\frac{1 + P_r / P_s}{1 - P_r / P_s} \right) \right]^{-1}$$
(2.22)

Here P_r , P_s and E_c are taken as positive quantities. Differentiating:

$$\frac{dP^{+}(E)}{dE} = P_{s} \left[2\delta \cosh^{2} \left(\frac{E - E_{c}}{2\delta} \right) \right]^{-1} = \frac{P_{s}}{2\delta} \operatorname{sech}^{2} \left(\frac{E - E_{c}}{2\delta} \right)$$
(2.23)

At the semiconductor ferroelectric interface:

$$\varepsilon_0 \varepsilon_s E_s = \varepsilon_0 \varepsilon_f E_f + P \tag{2.24}$$

Where ε_s is the relative permittivity of the semiconductor and E_s is the electric field in the semiconductor. Using Gauss's law

$$\varepsilon_0 \varepsilon_s E_s = -Q_s = \varepsilon_0 \varepsilon_f E_f + P \tag{2.25}$$

Differentiating:

$$dE_{f} = -\frac{dQ_{s}}{\varepsilon_{0}\varepsilon_{f} + \frac{dP}{dE_{f}}} = -\frac{dQ_{s}}{\varepsilon_{ferro}}$$
(2.26)

Where;

$$\varepsilon_{ferro} = \varepsilon_0 \varepsilon_f = \frac{P_s}{2\delta} \operatorname{sech}^2 \left(\frac{E - E_c}{2\delta} \right)$$
(2.27)

This equation is used in solving the Poisson's equation in the ferroelectric region.

$$\frac{d^2\Psi}{dx^2} = -\frac{\rho}{\varepsilon_f} \tag{2.28}$$

According to equation 2.2, the ferroelectric layer in the MFIS structure adds a memory function to the MOS capacitor. Due to the hysteretic nature of the ferroelectric, the *C-V* curves are now hysteretic too and are shown in Fig. 2.14. The width of the hysteresis loop is referred to as "memory window" and can have a maximum value (for the saturated hysteresis) of ~ $2E_c \cdot t_f$, where E_c is the coercive field and t_f is the thickness of the ferroelectric layer according to equation 2.29 [16].

Saturation MW = Shift in flatband voltage =
$$2E_c t_f \left(1 - \frac{\delta \varepsilon_f \varepsilon_0}{P_s}\right)$$
 (2.29)

It should be noted that the direction in the C-V curve is clockwise when the semiconductor is p-type, in contrast to the counterclockwise polarization hysteresis curve

Fig. 2.14. C-V curves of a metal-ferroelectric-insulator-semiconductor capacitor [11].
2.5 Current-Voltage Characteristics:

Taking into account the mechanisms of drift and diffusion, the current can be expressed in terms of the Quasi-Fermi potential (ϕ_{Fn}) as following:

$$I = -Wq\mu N_{inv} \frac{d\phi_{Fin}}{dx}$$
(2.30)

Where W is the channel width, N_{inv} is the inversion charge and μ is the channel mobility. Substituting for inversion charge, we obtain [16]:

$$I = \frac{-W}{L} \frac{\mu C_{stack}}{\beta^{2}} \left[\left(1 + \beta V + \frac{\beta t_{b}}{\varepsilon_{0} \varepsilon_{bg}} \right) P \left(\beta \phi_{sL} - \beta \phi_{s0} \right) - \frac{1}{2} \left[\left(\beta \phi_{sL} \right)^{2} - \left(\beta \phi_{s0} \right)^{2} \right] \right] - \frac{2}{3} a \left[\left(\beta \phi_{sL} \right)^{2/3} - \left(\beta \phi_{s0} \right)^{2/3} \right] + a \left[\left(\beta \phi_{sL} \right)^{1/2} - \left(\beta \phi_{s0} \right)^{1/2} \right] \right]$$
(2.31)

Where;

$$a = \sqrt{2} \left(\frac{\varepsilon_0 \varepsilon_s}{L.C_{stack}} \right) \tag{2.32}$$

The values of the surface potential, which are ϕ_{sL} and ϕ_{s0} , can be determined using the boundary conditions as following [17]:

$$\phi_{Fn}(source) = \phi_F + V_{bs} \tag{2.33}$$

$$\phi_{F_n}(drain) = \phi_F + V_{bs} + V_{ds}$$
(2.34)

Where, V_{bs} is the applied voltage, V_s is the applied transistor source voltage, and V_d is the applied transistor drain voltage. Simplistically, a FeFET can be viewed as a MOSFET combined with a ferroelectric capacitor as shown in Fig. 2.15.



Fig. 2.15. A MOSFET and a ferroelectric capacitor characteristics combine to give the FeFET I-V characteristics. The dashed curve represents an ideal ferroelectric [11].

Extensive numerical analyses are performed in Silvaco Ferro model and in other models such as BISIM3 as polarization is a function of electric field in the ferroelectric region to obtain I-V characteristics. Fig. 2.16 shows an example of I_{ds} -V_g characteristics and sub-loops of a FeFET.



Fig. 2.16 Simulated I-V sub-loops in the I_{DS} -V_G characteristics for the parameters shown. [11].

It is apparent that a FeFET has many similarities with the floating gate transistor, widely used in the Flash memory. In Flash, a high voltage is applied to the gate while grounding the drain to inject hot electrons into the floating gate. For erasing, the voltage is applied to the source while grounding the gate facilitated by the Fowler-Nordheim

tunneling. In FeFET, a gate voltage corresponding to the P+ polarization writes the state "1" while a negative voltage corresponding to the polarization state P- writes the state "0". In both cases, read process is same, applying a read voltage somewhere in the memory window where I_{on}/I_{off} ratio is maximum as shown in Fig. 2.17 [11].



Fig. 2.17. Reading performed by applying a read voltage somewhere in memory window: where I_{on}/I_{off} ratio is high; (a) for Flash; (b) for FeFET [11].

2.6 Depolarization, Charge Injection and Trapping Effects:

The depolarization electric field is an electric field that opposes the direction of polarization. This causes the polarization state in the ferroelectric film to become unstable. The depolarization field results from incomplete charge compensation at the ferroelectric/electrode interface which gives rise to a passive dielectric layer. In MFIS structure, the insulator layer and the semiconductor layer together play exactly the same role as the passive layer. The only difference is that the thickness of the layers is much thicker than the passive layer.



Fig. 2.18. Model of a MFIS ferroelectric capacitor with a depolarization field.

Referring to Fig 2.18 (b), the electric field seen by the whole structure is the sum of two components, the electric field in the ferroelectric film, E_f , and the electric field in the passive (buffer) layer, E_{IS} .

$$(t_{IS} + t_f)E = t_{IS}E_{IS} + t_fE_f$$
(2.35)

Where t_{IS} and t_f are the thicknesses of the passive layer and the ferroelectric layer respectively. When no field is applied across the structure, E=0

$$0 = t_{IS} E_{IS} + t_f E_f$$
(2.36)

$$E_{dp} = E_f = -\frac{t_{IS}E_{IS}}{t_f}$$
(2.37)

The continuity equation states that electric flux density is continuous.

$$D_{IS} = \varepsilon_{IS} E_{IS} = D_f = \varepsilon_f E_f = P \tag{2.38}$$

Where symbols D refer to the electric flux densities in each region and P is the spontaneous polarization in the ferroelectric layer.

$$E_{dp} = -\frac{t_{IS}P}{t_f \varepsilon_{IS}}$$
(2.39)

Referring to the schematic in Fig. 2.19, where the ferroelectric layer is represented as one capacitor with a certain spontaneous polarization, P, and an amount of charge compensated at the electrodes, Q_F , with total capacitance C_f . The insulator (buffer) and semiconductor layers are represented by a capacitor C_{IS} . The voltage drop across the ferroelectric layer is represented in two terms: one due to its capacitance and the voltage applied across it, V_f , and another due to its internal spontaneous polarization. Note that all capacitances are expressed as capacitance per unit area.



Fig. 2.19. A schematic capacitance design of the MFIS structure [18].

$$C_{IS}V_{IS} = P + C_f V_f \tag{2.40}$$

Where;

$$V = V_{IS} + V_f \tag{2.41}$$

By solving for V_f, we obtain:

$$V_f = \frac{C_{IS}V - P}{\left(C_{IS} + C_f\right)} \tag{2.42}$$

Including the magnitude of polarization P as $E_{dp}\epsilon_f$ and substituting for capacitances as permittivity/thickness:

$$V_{f} = \frac{V}{1 + \frac{\varepsilon_{f}}{\varepsilon_{IS}} \frac{t_{IS}}{t_{f}}} - \frac{E_{dp}}{\frac{\varepsilon_{IS}}{\varepsilon_{f}} t_{IS}} + \frac{1}{t_{f}}}$$
(2.43)

Note that if the thickness of insulating layer, t_{IS} goes to zero, $V_f=V$, and all of the applied voltage is dropped across the ferroelectric layer, and no depolarization effect happens. It can be observed that when the source and the gate are shorted, V=0, the voltage across the ferroelectric is E_{dp} (proportional to polarization P) is reduced by some function of the relative permittivities of the materials in the stack.

$$V_{f} = -\frac{E_{dp}}{\frac{\varepsilon_{IS}}{\varepsilon_{f}t_{IS}} + \frac{1}{t_{f}}}$$
(2.44)

It is evident from the above equations, that a higher ε_{IS} and a smaller t_{IS} are desired to reduce the effect of the insulating layers on the polarization of the ferroelectric. This makes it possible to invert the channel at a lower voltage and improve on/off ratio. To minimize depolarization field, buffer layer capacitance must be as large as possible [18].

The other important issue of ferroelectric and semiconductor interfaces is the charge injection, which typically occurs from the semiconductor to the ferroelectric gate region during the switching process in FeFETs as seen in Fig. 2.20 [19]. Ferroelectric polarization attracts electron injection towards the ferroelectric/insulator interface from both the gate electrode and the semiconductor channel. Electron injection and trapping in the dielectric stack cause local charge compensation in the ferroelectric, reducing the polarization. Insulating buffer layers on both sides of the ferroelectric layer can reduce

this problem, but would increase the depolarization field and the applied field that is necessary to polarize the device.



Fig.2.20 Gate leakage effects in MFIS FeFET devices (a) Inverted semiconductor immediately after polarization, and (b) depolarization after time [18].

Despite the high energy bandgap in insulators and a large thickness, charge transport does occur and can lead in several cases to an unwanted leakage current. The leakage current through the gate stack in the case of the FeFET can reduce the data retention time (polarization). The charge transport in insulators can be attributed to a number of mechanisms as can be seen in Fig. 2.21 extensively studied for conventional CMOS with thin gate dielectric. They are divided in the injection mechanisms, such as tunnel and thermionic injection, and the transport mechanisms, such as Poole-Frenkel, hopping, drift and diffusion. The condition for drift is the existence of enough free states in the valence or conduction band, and for diffusion, a carrier concentration gradient.



Fig. 2.21. Various charge transport mechanisms in insulators [11].

Based on these discussions, following observations are summarized:

- Buffer layer reduces the problem of intermixing silicon and ferroelectric
- Gate voltage is divided according to capacitance ratio of the buffer layer and the ferroelectric layer
- To minimize depolarization field, buffer layer capacitance must be as large as possible
- Too thick ferroelectric makes the operation voltage too high
- The effect of charge injection can be minimized by employing an engineered buffer sandwiched between the silicon and the ferroelectric layer
- Leakage current between ferroelectric and buffer, removes the charges, hence the stored data cannot be readout

It is inferred that optimization of buffer layer is extremely important.

2.7 Evolution of FeFETs on Conventional Perovskites:

Ferroelectric FETs have been proposed in 1957 as an alternative to FeRAMs, which suffer from data loss. FeFETs have been being studied for more than fifty years. PZT and SBT ferroelectric materials have been studied for a long time. Roy, Dhar and Ray (2007) studied the performance of SBT based FeFET devices. In their study, they fabricated a FeFET with 280 nm SBT ferroelectric layer. The general structure of their device was Al/SBT/HfO₂/Si. In their study, they found that a large memory window could be accomplished by using 12 nm of HfO₂ buffer layer as seen in Fig. 2.22 [20].



Fig. 2.22. C-V characteristics of Al/SBT (280 nm)/HfO₂/Si (a) with 3 nm HfO₂ buffer layer (b) with 12 nm buffer layer, and (c) with 18 nm buffer layer [20].

Phan Trong Tue et al. (2010) fabricated a PZT-based FeFET with indium tin oxide (ITO)/PZT/ SrRuO₃(SRO)/Pt stacked structure. The gate length of fabricated device was 60 μ m and the gate width was 20 μ m. Fig. 2.23 shows the hysteresis loop of this device [19].



Fig. 2.23. I-V characteristics of the PZT-based FeFET using ITO/PZT/SRO/Pt structure [18].

Chai et al. (1995) studied the relation of the ferroelectric thickness and the niobium doping levels in capacitor memories. They found that reducing the ferroelectric thickness (in 0.3 μ m range) by a factor of 2 should be compensated by increasing the doping up to 5% to reduce the effect of leakage in capacitor memories. Their study focused only on capacitor memories [16]. Therefore, it is significant to understand the scaling effect of ferroelectric gates in field effect Transistors. Fig. 2.24 shows the effect of doping on the hysteresis loops of capacitor memories [17].



Fig. 2.24: Measured hysteresis loops of ferroelectric films with different niobium doping levels [17].

Using an insulator layer forms two serial capacitors (voltage divider) as seen in Fig. 2.25. The effect of this voltage divider can be reduced by using high-k dielectric materials in the insulator [21].



Fig.2.25. Effect of voltage divider due to using a buffer layer.

Kim et al. (1998) investigated the effect of the insulator layer on the I-V characteristics of FeFETs. They studied three different insulating materials, which are cerium oxide (CeO₂), yttrium oxide (Y₂O₃) and silicon dioxide (SiO₂). Their study focused on FeFETs with Strontium Bismuth Tantalate $SrBi_2Ta_2O_9$ (SBT) ferroelectric material. Their results showed that using CeO₂ and Y₂O₃ insulation materials effectively reduced the charge injection between semiconductor and SBT interface and reduced the effect of voltage divider effect [22]. There are other common high-K dielectric materials that can be investigated such as hafnium oxide (HfO₂) and strontium tantalate (SrTa₂O₆). Fig. 2.26 (a) and (b) shows the I_d-V_d curves of the FeFET with yttrium oxide (Y₂O₃) and silicon dioxide (SiO₂) layers, respectively.



Fig. 2.26. I_d-V_d characteristics of the FeFET with (a) SiO₂ (b) Y₂O₃ dielectric layers [22].

Roy, Dhar and Ray (2007) studied the effect of using hafnium oxide (HfO₂) as a buffer layer for FeFETs. Their study depended on FeFETs with 280nm thick SBT ferroelectric material and aluminum gate metal. Final results showed that FeFETs with HfO₂ buffer layers had larger memory windows than devices with no buffer layer as seen in Fig. 2.27. They found also that the current leakage decreased with increasing the HfO₂ buffer layer thickness [20].



Fig. 2.27. C-V characteristics of FeFET with HfO₂ and SiO₂ dielectrics [20].

2.8 Limitations of PZT and SBT for FeFET Applications:

Commonly used perovskite ferroelectrics such as PZT and SBT are high dielectric constant (high-k) materials (ϵ_r ~250) in thin films. A high-k material, although favored as a gate dielectric, is not a desirable property for the ferroelectric in the FeFET, because of the low-k dielectric buffer layer that is always present in the FeFET gate stack. The dielectric's lower permittivity (lower capacitance) results in a higher voltage drop across the buffer layer compared to that across the ferroelectric. PZT and SBT also suffer from an increase in coercive fields as thickness is scaled down [23]. These materials possess only limited compatibility with standard semiconductor processing. Integration into transistor devices is only possible with interfacial barriers and FE layers thicker than 100 nm need to be used in order to achieve non-volatility. Hence, no easy scaling of the devices according to current technology node requirements can be realized. Thicker films also lead to more fringing effects which cause degradation of sub-threshold characteristics. Fig. 2.28 shows the main concept of fringing [24].



Fig. 2.28 Fringing effects due to thicker gate dielectric [24].

2.9 Ferroelectricity in Silicon Doped Hafnium Oxide (Si:HfO₂):

FeFETs have been being studied for more than fifty years but the ideal device remains elusive. This is because many issues in gate stack and interface states densities. Discovery of ferroelectricity in doped hafnium oxide (HfO₂) has opened doors for realizing high performance FeFETs.

Boscke, Muller et al. (September 2011) studied ferroelectricity in thin films of silicon doped hafnium oxide (Si:HfO₂). These films were 10nm thick with less than 4 mol. % of SiO₂. They observed that the large band offset between Si and HfO₂ allows for minimal current leakage and it is otherwise thermodynamically compatible with silicon technology, allowing for contact without the need for a thick buffer layer [25].

Sun and Zheng (October 2011) studied the effect of the buffer layer thickness on MFIS-FeFETs. Their study focused on SiO_2 dielectric layers. They studied a FeFET device with 5 μ m channel length and 5nm thick SiO_2 . Their results showed that the I-V characteristics of the FeFET became worse as the SiO_2 thickness increased because of the retention loss [26].

Tingting Feng et al. (2011) studied a MFIS-FeFET with 2μ m channel length, 400 nm thick ferroelectric and 5nm thick HfO₂ dielectric. Their study focused on using Nd-doped Bismuth Titanate B_{3.15}Nd_{0.85}Ti₃O₁₂ (BNdT) ferroelectric material, which has a large remnant polarization (P_r). They used Silvaco software to study all the performance parameters such as gate voltage and buffer layer thickness. Their final results showed that there was insignificant charge injection between Si and ferroelectric material because of the use a thin layer of HfO₂ as a buffer layer. The BNdT ferroelectric layer showed a wide memory window as seen in Fig. 2.29 [27].



Fig. 2.29. Polarization hysteresis loop of the simulated FeFET [27].

Ekaterina Yurchuk et al. (2012) fabricated a sub-0.3 μ m (260nm) FeFET with 9nm thick Si:HfO₂. The general stack form of their device was poly-Si/TiN/Si:HfO₂ /SiO₂ /Si. Their results showed that the FeFET performance could be improved by doping the 9nm thick HfO₂ films with 4.4 mol. % SiO₂ as shown in Fig. 2.30 [28].



Fig. 2.30. Improved polarization by doping HfO₂ with 4.4 mol. % SiO₂ [28].

Stefan Mueller et al. (2013) studied the performance of Si:HfO₂ FeFETs based on a 28nm bulk technology. Their study used Sentaurus TCAD simulations where material parameters such as coercive field, remnant polarization, saturation polarization, and permittivity were determined experimentally and then input into the simulation. The

accuracy of their model was verified on Metal-Ferroelectric-Metal (MFM) structures. Their study focused on two different ferroelectric material thicknesses, which are 10nm and 30nm [29]. The results of hysteresis loops of these structures are shown in Fig. 2.31.



Fig. 2.31. The experimental verification of TCAD simulations [29]

The 10 nm thick ferroelectric layer has larger remnant polarization compared to the 30 nm thick layer. The remnant polarization values are 9μ C/cm² and 2μ C/cm² for 10nm and 30 nm thick ferroelectric layers, respectively [29]. Since 10nm ferroelectric layer has a larger remnant polarization, it showed much more pronounced depolarization compared to the 30nm layer as seen in Fig. 2.32. Their experimental results and their simulations showed the remnant polarization (P_r) of Si:HfO₂ increased by decreasing the layer thickness. The thinner device was able to operate at lower voltages (5 V as compared to 6 -7 V for the thicker device).



Fig. 2.32. The I_d - V_g curves of the simulated FeFET device (a) with 10 nm thick ferroelectric layer (b) with 30 nm thick ferroelectric layer [29].

David J. Frank et al (2014) studied the quantum metal FeFET (QMFeFET). They introduced a mathematical module to achieve steep sub-threshold slope FeFET by using a very thin metal or a quantum metal. Their model showed that a QMFeFET with very steep sub-threshold, which was about 2mV/decade over 11 decades, could be accomplished. In their study, two approaches have been introduced as seen in Fig. 2.33 (a) and (b). These approaches include a QMFeFET with and without a thin buffer layer between the semiconductor and the quantum metal [30].



Fig. 2.33. Structure of the QMFeFET (a) with buffer layer (b) without buffer layer [30].

The International Technology Roadmap for Semiconductors (ITRS) 2013 emerging research devices edition indicates that there is a need for more work to be done to improve FeFETs performance parameters such as retention time and integrating the technology into actual CMOS based devices [31].

The last three years show that extraordinary improvements have been accomplished in FeFET devices. It has been shown that FeFET devices can be fabricated down to the 28nm node in modern factory lines. This indicates that optimization of shorter channel devices is certainly warranted. However, much research, developments, and optimizations are still needed since FeFET devices are very variable prospect in the non-volatile memory market.

2.10 Research Objectives:

After conducting the literature study presented above, the following research objectives were proposed and carried out in this study;

- 1. Perform simulations of 26 nm FeFETs utilizing the data for Si:HfO₂ reported in the literature using SILVACO ATLAS software. Obtain drain current versus gate voltage characteristics by using the device parameters such as channel doping, source drain doping and junction depth, and gate electrode in simulations according to state of the art 26 nm NMOS.
- Investigate the effects of ferroelectric thickness, buffer layer thickness and buffer layer permittivity on the memory window of FeFET. Investigate non-ferroelectric pure hafnium oxide as a buffer layer and compared with SiO₂ and Si₃N₄ as buffer layer materials.

CHAPTER 3 – SILVACO ATLAS SIMULATIONS METHODOLOGY

This chapter focuses on Silvaco Atlas software. It gives an introduction to Silvaco software. Then, it follows an explanation of Silvaco atlas parameters. The ferroelectric used model is discussed in this chapter.

3.1 Silvaco:

Silvaco is a TCAD software package that can be used to achieve device and process simulations. Fig. 3.1 shows the main modules of the Silvaco software [32].



Fig. 3.1. Silvaco main modules.

- Athena: It is considered as a process software module. It is basically used to treat serial steps of devices fabrication. The most common processes that can be treated include deposition, diffusion, ion implantation, etching, lithography, silicidation of semiconductor materials and oxidation. Athena provides a good alternative for practical experiments that usually cost a lot of money.
- Atlas: It is a good tool to study behavior of semiconductor devices such as electrical, optical and thermal behavior. It provides accurate simulations in 2D and 3D to study

and analyze AC, DC and time domain responses for all semiconductor based technologies.

- Mercury: It is a group of device simulations that include MESFET and HEMT devices. It contains FastBlaze, Mocasim, FastNoise and FastDevEdit device simulation products. FastBlaze simulator is used to generate accurate and proper electrical characteristics of MESFET and HEMT devices by using physics based calculations. Mocasim is mainly used to achieve accurate calculations of wurtzite and zincblende semiconductors fundamental electron transport properties.
- Virtual Wafer Fab (VWF): It is used to emulate and automate physical wafer manufacturing processes. VWF tools are effective in facilitating the input, run-time optimization, execution and results into a flow managed through a database.

Physically based simulations, which are different from empirical modeling, are typically used in Silvaco. The simulated devices are represented onto a two dimensional grid, which consists of a number of nodes. To simulate the transport of carriers, a set of fundamental semiconductor differential equations are solved on this two dimensional grid. These differential equations are solved by integrating relevant physics. The most common equation can be classified to transport equations, continuity equations and Poisson's equation [32].

Poisson's equation shows the relation between electrostatics potential, electric field and electrostatic charges, which include mobile and fixed charges. This equation can be expressed as following:

$$\Delta^2 \Phi = -\Delta E = \frac{\rho}{\varepsilon} \tag{3.1}$$

$$\Delta^2 \Phi = -\frac{q}{\varepsilon} \left(p - n + N_d^+ - N_a^- \right)$$
(3.2)

Where Φ represents the electric potential, E represents the electric field, ρ represents the charge density, and ϵ is the semiconductor permittivity. In equation 3.2, q represents the electron charge, which is about -1.602×10⁻¹⁹ C, p and n represent the densities of free holes and electrons respectively, and N_d⁺ and N_a⁻ are the charge densities of ionized donors and acceptors, respectively.

The drift-diffusion model can be used to express the transport equation as following:

$$J_{p}(x) = q\mu_{p}p(x)E(x) + qD_{p}\frac{dp(x)}{dx}$$

$$J_{n}(x) = q\mu_{n}n(x)E(x) - qD_{n}\frac{dn(x)}{dx}$$
(3.3)
(3.4)

These equations are a combination of drift current and diffusion current components. In equation 3.3, μ_p is the hole mobility and D_p is the hole diffusivity. In equation 3.4, μ_n is the electron mobility and D_n represents the electron diffusivity. Einstein relation expresses the relation between diffusion coefficient and mobility as following:

$$\frac{kT}{q} = \frac{D}{\mu} \tag{3.5}$$

Where D is the diffusion coefficient and μ is the mobility. The following equations express the carrier continuity for holes and electrons.

$$\frac{\partial p}{\partial t} = G_p - R_p - \frac{1}{q} \Delta J_p$$

$$\frac{\partial n}{\partial t} = G_n - R_n - \frac{1}{q} \Delta J_n$$
(3.6)
(3.7)

Where, G_p and G_n represent the generation rates of excess holes and electrons, respectively, J_p and J_n are the current densities of holes and electrons and R_p and R_n represent the recombination rates of holes and electrons [32]. The permittivity model is explained in section 3.3.

3.2 Silvaco Atlas:

In Silvaco Atlas, it is significant to specify physical structure, physical model and bias conditions of the simulated device. Fig. 3.2 shows the inputs and outputs of Silvaco atlas.



Fig. 3.2. Inputs and outputs of Silvaco Atlas [33].

Atlas typically uses two types of input file. First type is the structure file that is used to define the structure of the simulated device. Second type is the text file, which includes all the atlas commands. The key function of the structure file is to store the 2D and 3D data that are related to the values of solution variables [32]. The general syntax of an input statement is Atlas is:

<statement><parameter>=<value>

The parameter value in Atlas can be logical, character, real or integer. Statements are generally classified to five groups. These groups include structure specification, material model specification, numerical method selection, solution specification and results analysis. Table 3.1 shows Atlas input specifications.

Group	Statement		
	mesh		
Structure Specification	region		
	electrode		
	doping		
	material		
Material Models Specification	models		
	contact		
	interface		
Numerical Method Selection	method		
	log		
Solution Specification	solve		
	load		
	save		
Results Analysis	extract		
	tonyplot		

 Table 3.1: Input specifications of Silvaco Atlas [32]

Output files of Atlas can be classified to three types, which are run-time output, log file output and structure file output. Run-time output files basically give the messages of warnings, progress and errors of simulations. Log file outputs (.log) are used to store the terminal characteristics that are calculated by Silvaco Atlas. In DC simulations, these

calculations include current and voltages at electrodes of the simulated device. In transient simulations, log files are used to store time. In AC simulations, this type of output files is used to save the conductance, the small signal frequency and capacitance. Structure files (.str) are used to provide an image of the simulated device at a certain bias point. Doping profiles, band parameters, electric fields and electron concentrations can be effectively displayed using structure file outputs.

3.3 The Ferroelectric Permittivity Model in Atlas:

To simulate polarization and hysteresis effects of ferroelectric materials, the ferroelectric model in Atlas should be used in the simulation code. This model can be enabled by setting the "FERRO" parameter in the "MODELS" statement. The permittivity, which is used in Poisson's equation, is expressed as derived in equation 2.27 as following [32]:

$$\varepsilon(E) = ferro. epsf + \frac{ferro.ps}{2\delta} \cdot \sec h^2 \left[\frac{E - ferro.ec}{2\delta} \right]$$
 (3.8)

Where, E is the electric field, *ferro.epsf* is the permittivity. δ can be mathematically expressed as following:

$$\delta = ferro.ec \left[\log \left(\frac{1 + \frac{ferro.pr}{ferro.ps}}{1 - \frac{ferro.pr}{ferro.ps}} \right) \right]^{-1}$$
(3.9)

The ferroelectric parameters, which are *ferro.pr, ferro.ps, ferro.epsf* and *ferro.ec,* can be specified in the "MATERIAL" statement. Each material has different parameters

depending on its characteristics. Table 3.2 shows the default values of the ferroelectric parameters [32].

Statement	Parameter	Default Value	Unit
MATERIAL	Ferro.ec	0.0	V/cm
MATERIAL	Ferro.epsf	1.0	
MATERIAL	Ferro.ps	0.0	C/sqcm
MATERIAL	Ferro.pr	0.0	C/sqcm

 Table 3.2: Default values and units of ferroelectric parameters [32]

The permittivity in equation 3.8 can be redefined by using the C-Interpreter. To define the file that contains the C-function, the *"f.ferro"* parameters should be included in the "MATERIAL" statement. The key function of this step is to allow the permittivity to be position. The dipole polarization can be expressed with respect to the electric field as following:

$$\frac{dP_d}{dE} = \Gamma \frac{dP_{sat}}{dE}$$
(3.10)

Where P_d represents the position dependent dipole polarization and P_{sat} is the saturated loop polarization. Γ is a unity function, and it corresponds to the default model. The Γ function can be modified to be more general by specifying the "*unsat.ferro*" parameter in the "MODELS" statement. Γ can be expressed in this case as following:

$$\Gamma = 1 - \tanh\left[\left(\frac{P_d - P_{sat}}{\xi P_s - P_d}\right)^{1/2}\right]$$
(3.11)

Where ξ signal depends on the direction of electric field. It equals to "+1" for increasing electric field and "-1" for decreasing electric fields.

3.4 Methodology Specifications:

To simulate and study the performance of a short channel FeFET, it is important to proceed through the following steps in the proper order.

 Defining the device structure: Device structure is typically defined by the mesh of each region and specifying these regions according to the desired device structure.

For example:

region num=1 silicon y.min=0.0 region num=2 material=HfO2 y.max=0.0 y.min=-0.00005 region num=3 oxide y.max=-0.00005 y.min=-0.010 region num=4 oxide y.max=-0.010 y.min=-0.0101

Defining electrodes for source, drain and gate contacts: Electrodes are typically

defined by locating the desired electrode with its dimensions. For example:

electrode num=1 material=NiSi name=source y.max=0.0 x.max=0.002 electrode num=2 material=NiSi name=drain y.max=0.0 x.min=0.026409 electrode num=3 material=TiN name=gate top x.min=0.002841 x.max=0.025568 electrode num=4 name=substrate bottom

Defining doping values for source, drain and substrate: Doping can be obtained

by specifying the doping type and its value. For example:

doping uniform conc=3e16 p.type doping gaus conc=1e19 n.type x.right=0.004066 char=0.0008 doping gaus conc=1e19 n.type x.left=0.024343 char=0.0008

 Defining the ferroelectric material: Ferroelectric materials are defined by using the order "*ferro*". In addition, the permittivity characteristics, i.e. remnant polarization, spontaneous polarization, critical electric field and zero field relative permittivity, should be defined for each ferroelectric layer. The following numbers are measured by Stefan Mueller et al. (2013) [29]. For example:

model region=3 ferro material region=3 ferro.ec=1.1e6 ferro.pr=9.0e-6 ferro.ps=9.5e-6 ferro.epsf=32

Obtaining I-V characteristics: To obtain I-V curves, it is significant to use an accurate method. For example:

method gummel newton itlim=25 trap maxtrap=12 vsatmod.inc=0.01 carriers=2 output con.band val.band band.param e.mobility h.mobility

This method consists of several parts. These parts include:

- ✓ method gummel newton: To obtain an improved initial guess for the newton solution scheme.
- \checkmark itlim : Controlling the maximum number of iterations.
- ✓ Maxtrap: Specifying the number of times the trap procedure will be repeated.
- ✓ Vsatmod.inc: Specifying that the derivatives of the negative differential mobility will not be for potential that is less than the value specified by vsatmod.

The I-V curve can be obtained by drawing the forward and reverse sweep of the FeFET. Then, the threshold voltage (V_T) shift can be effectively obtained. For example:

```
solve
```

CHAPTER 4 – RESULTS AND ANALYSIS

This chapter focuses on the results of the simulated devices. Four different devices have been simulated to study the effect of ferroelectric thickness on the performance of the FeFET. The purpose of these simulations is to suggest that it is possible to get short channel FeFETs with high performance by using Si:HfO₂ as a ferroelectric material.

4.1 Device Parameters (n-FeFET Parameters):

This device was designed with 26 nm gate metal length. Table 4.1 shows the parameters of the simulated device.

Parameter	Value
P-well Doping (cm ⁻³)	1×10 ¹⁷
S/D Doping (cm ⁻³)	1×10 ¹⁹
Junction depth (nm)	10
Gate Metal Length (nm)	26
HfO ₂ Buffer Layer Thickness (Å)	8
Gate Electrode	TiN
S/D Electrodes	NiSi
Ferroelectric Layer	Si:HfO ₂

Table 4.1: Parameters of the simulated device

Since punchthrough typically occurs at lower voltages in the device with deeper sourcedrain junction depths, the S/D depths were designed to be too shallow (10nm). Titanium nitride (TiN) was used as a gate electrode to reduce gate depletion effect. Nickel silicide (NiSi) was used to reduce S/D series resistance in order to avoid the decreasing in the drive current (I_{drive}). Silicon doped hafnium oxide (Si:HfO₂) was used as a ferroelectric material. Si:HfO₂ material was studied by Stefan Mueller et al. (2013), and they found that the remnant polarization of this material considerably increased with decreasing thickness. This means that it is possible to achieve short channel FeFETs that are able to operate at lower voltages. In this work, four different ferroelectric thicknesses were used. Table 4.2 shows these thicknesses with the permittivity characteristics of each thickness and the theoretical maximum memory window (MW_{max}) that can be accomplished at each thickness. Permittivity characteristics of Si:HfO₂ material have been measured by Stefan Mueller et al for 10 nm and 30 nm thicknesses. A calculator was developed to estimate these characteristics for any thickness as seen in Appendix A.

Table 4.2: Permittivity characteristics of the Si:HfO₂ ferroelectric material for different thicknesses and the calculated maximum memory window values

Ferroelectric Thickness	P _r (μC/cm ²)	P _s (μC/cm ²)	E _c (MV/cm)	ε _f	t _b (nm)	ε _b	MW _{max} =2E _c t _f
15 nm	7.25	7.63	1.05	30.25	0.8	25	3.15 V
12 nm	8.3	8.75	1.08	31.3	0.8	25	2.59 V
10 nm	9	9.5	1.1	32	0.8	25	2.2 V
8 nm	9.7	10.25	1.12	32.7	0.8	25	1.9 V

Fig. 4.1 shows the main structure of the simulated Si:HfO₂ FeFET device.



Fig. 4.1. Main structure of the simulated FeFET (dimensions in µm).

4.2 Effect of the Ferroelectric Layer Thickness:

The key features of these simulations is using silicon doped hafnium oxide (Si:HfO₂) as a ferroelectric layer. Four transistor geometrics were created, the first one has 15 nm, the second one has 12 nm, the third one has 10 nm, and the last one has 8 nm of Si:HfO₂ as a ferroelectric layer. All these devices have 8 Å of HfO₂ as a buffer layer. The main purpose of simulating devices with different ferroelectric thicknesses was to study the effect of the ferroelectric thickness on the performance of the FeFET. The gate voltage was swept from -7 V to +7 V for all FeFET devices. Then, the sweep amplitude was decreased to 0 V while keeping the drain voltage at 0.1 V. Fig. 4.2 and 4.3 show the simulated devices and the I-V hysteresis loops, respectively.



Fig. 4.2. Simulated FeFET device (a) with 15 nm (b) with 12 nm (c) with 10 nm, and (d) with 8 nm thick ferroelectric layer (dimensions in μ m).



Fig. 4.3. Effect of ferroelectric layer thickness.

Since the remnant polarization of Si:HfO₂ considerably increased by decreasing the layer thickness, the memory window (MW) decreased. The advantage of using thinner layer of Si:HfO₂ ferroelectric material is the possibility of accomplishing ultra low-power FeFET devices. As seen in Fig. 4.3, the Memory window (MW) decreased from 1.4 V to about 0.85 V as the ferroelectric layer thickness was decreased from 15 nm to 8 nm, respectively. Table 4.3 shows a comparison between the simulated devices.

Ferroelectric Layer Thickness	Memory Window (MW)
15 nm	1.4 V
12 nm	1.25 V
10 nm	1.1 V
8 nm	0.85 V

Table 4.3: Comparison of results of the simulated devices.

4.3 Effect of Buffer Layer Thickness:

The FeFET device, which has 10 nm thick ferroelectric layer, has been simulated with 8 Å thick HfO₂ buffer layer, with 5 Å thick HfO₂ buffer layer and without buffer layer. These simulations have shown that the FeFET device with no buffer layer has the largest memory window. This means removing the buffer layer has reduced the effect of voltage divider. Fig. 4.4 and 4.5 show the simulated device and the hysteresis loops, respectively.



Fig. 4.4. FeFET device (a) with 8 Å thick HfO₂ buffer layer (b) with 5 Å thick HfO₂ buffer layer, and (c) without buffer layer (dimensions in μ m).



Fig. 4.5. I-V hysteresis loops of the FeFET device with 8 Å thick HfO₂ buffer layer, with 5 Å thick HfO₂ buffer layer and without buffer layer.

As seen in Fig. 4.5, the higher thickness, which is 8 Å, reduced the buffer layer capacitance and caused a higher voltage drop across the buffer layer and a smaller voltage drop across the ferroelectric layer. Table 4.4 shows the effect of the HfO_2 buffer layer thickness on the memory window value.

Buffer layer Thickness	Memory Window (MW)		
8 Å	1.1 V		
5 Å	1.2 V	_	
No Buffer Layer	1.22 V	_	

Table 4.4: Effect of buffer layer thickness on the FeFET performance.

4.4 Effect of the Buffer Layer Permittivity:

When buffer layers with low permittivity were used instead of the hafnium oxide (HfO_2) buffer layer, the total capacitance decreased. Thus, the memory window of the FeFET (with 10 nm ferroelectric) decreased. Fig. 4.7 shows the degradation in memory window value when the hafnium oxide (HfO_2) was replaced by other materials. These materials are silicon oxide (SiO_2) and silicon nitride (Si_3N_4) .

The total capacitance of an MFIS-FeFET is given by:

$$C_{total} = \left(\frac{1}{C_f} + \frac{1}{C_b} + \frac{1}{C_s}\right)^{-1}$$
(4.1)

Where,

$$C_f = \frac{\varepsilon_f A_f}{t_f} \tag{4.2}$$

$$C_b = \frac{\varepsilon_b A_b}{t_b}$$
(4.3)

Where,

$$\varepsilon_f = \varepsilon_0 \varepsilon_{f,r} \tag{4.4}$$

$$\varepsilon_b = \varepsilon_0 \varepsilon_{f,b} \tag{4.5}$$

A is the area in square meters, and t_f is the ferroelectric layer thickness. Fig 4.6 and 4.7 show the simulated FeFET with different buffer layer materials and the I-V hysteresis loops, respectively.



Fig. 4.6. FeFET device with 8 Å of (a) HfO_2 buffer layer (b) SiO_2 buffer layer, and (c) Si_3N_4 buffer layer (dimensions in μm).


Fig. 4.7. I-V hysteresis loops of the FeFET device with 8 Å of HfO_2 buffer layer, SiO₂ buffer layer, and Si₃N₄ buffer layer.

Table 4.5 shows the effect of the buffer layer permittivity on the FeFET performance.

Fable 4.5: Effect of buffer	layer permit	tivity on the F	'eFET	performance.
	v 1			

Buffer Layer Material	Dielectric Constant [34]	Memory Window (MW)
HfO ₂	25	1.1 V
SiO ₂	3.9	0.85 V
Si ₃ N ₄	7	0.95 V

4.5 Effect of the Applied Electric Field:

When the applied electric field was less then the coercive field of the ferroelectric layer, minor hysteresis loops with smaller memory window were observed. The memory window increased as the applied electric field increased as seen in Fig. 4.8. The I-V

curves were obtained by keeping the drain voltage constant and sweeping the gate voltage between the write-voltage (V_{dd}) and the erase-voltage ($-V_{dd}$).



Fig. 4.8. I-V hysteresis loops of the FeFET device with different applied electric fields.

4.6 Effect of Polarization on Threshold Voltage:

Previous results have shown that the hysteresis effect of the Si:HfO₂ ferroelectric material has produced a significant shift in the transistor threshold voltage. This shift shows that the hysteresis effect in the ferroelectric polarization has resulted in different threshold voltages depending upon the direction of the gate sweep. Fig. 4.9 and 4.10 show the transistor with no ferroelectric material and the resulted I-V curve.



Fig. 4.9. Transistor device with no ferroelectric layer (dimensions in µm).



Fig. 4.10. I-V curves with 10 nm thick ferroelectric layer and with no ferroelectric layer

As observed in Fig. 4.10, the sub-threshold slop is better in FeFET due to internal voltage amplification. The improvement in the sub-threshold voltage due to incorporating a ferroelectric layer is called internal voltage amplification due to negative capacitance.

CHAPTER 5 – CONCLUSIONS AND FUTURE WORK

This chapter summarizes the key points of this study. Moreover, It suggests future studies in the field of ferroelectric-based devices.

5.1 Conclusions:

Ferroelectric Field Effect Transistors (FeFETs) have been introduced as the best solution to avoid data loss during read out processes in FeRAMs. Since the reading process depends on the sensing of the conductance in the channel region in FeFETs, data can be kept with no change.

Lead Zirconate Titanate (PZT) and Strontium Bismuth Tantalate (SBT) ferroelectric materials have been studied for a long time. The main disadvantage of these ferroelectric materials is that the coercive fields considerably increase as thickness is scaled down. FeFET devices that have PZT or SBT ferroelectric materials suffer from charge injection from semiconductor to ferroelectric material. Therefore, it is required to incorporate a dielectric layer between the semiconductor and the ferroelectric layer to reduce the charge injection effect. Using silicon doped hafnium oxide (Si:HfO₂) as a ferroelectric layer has successfully reduced this effect; thus, there is no need for using a buffer layer. Since the dielectric layer causes a voltage drop due to the formation of two serial capacitors, using Si:HfO₂ makes it possible to avoid this unwanted effect. Another disadvantage of using a buffer layer is that a depolarization field can be created. This effect can be avoided by using Si:HfO₂ as a ferroelectric layer.

The simulated Si:HfO₂ FeFET has shown large memory windows even with a very thin ferroelectric layer. When the ferroelectric thickness was 10 nm, the memory window was about 1.22 V even without a buffer layer. This means that the Si:HfO₂ can

effectively reduce the current leakage. When low permittivity buffer layers were used, the memory window of the FeFET, which has 10 nm ferroelectric layer, was degraded to less than 1 V.

The discovery of ferroelectric properties in silicon doped hafnium oxide (Si:HfO₂) has resolved the obstacles of limited scalability and CMOS incompatibility of conventional ferroelectric materials. The gap to the logic technology roadmap could be finally closed by using novel material as a ferroelectric material. Si:HfO₂ makes it possible to accomplish highly scaled and ultra low-power FeFETs.

5.2 Future Work:

Two components of the Si:HfO₂ FeFET device are in need for further study. The first is the negative capacitance effect of Si:HfO₂ material in FeFETs. The negative capacitance FETs (NCFETs) can be used as step-up voltage transformers. This novel technique can reduce the sub-threshold swing (SS) to less than 60 mV/decade. The second component is the surface potential of the NCFeFET devices.

To accomplish this study, the structure of the device should be modified to make it possible to access the negative capacitance region. In other words, the semiconductor capacitance should be reduced to make it smaller than the ferroelectric capacitance. It is significant to develop a proper surface potential model for Silvaco Atlas to achieve effective simulations of NCFETs. Another area for future work is to replace the Si:HfO₂ material by aluminium doped hafnium oxide (Al:HfO2). This material can be studied as a ferroelectric material. By selecting either a divalent or trivalent doping metal, the electron affinity of the dielectric material can be controlled, while also providing a higher dielectric constant material then silicon dioxide. It is significant to have some permittivity measurements to simulate Al:HfO₂ FeFET devices using Silvaco Atlas . In addition, Al:HfO₂ Ferroelectric Tunnel Junction (Al:HfO₂ FTJ) is a good area to be studied in the future. In Ferroelectric layer. The resistance of this kind of devices, which is known as tunneling electroresistance (TER), mainly depends on the direction of the polarization. There are at least two mechanisms of the TER effect that can be studied in the future. The first mechanism is the change in the electrostatic potential across the ferroelectric layer. The second suggested mechanism is the change in the attenuation constant of the barrier. Fig. 5.1 shows the main suggested subjects that can be studied in the future.



Fig. 5.1. Suggested subjects for future work.

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Appendix A

Ferroelectric Parameters Calculator

clc;

clear;

close all;

t=10;

x=0.35;

y=0.37475;

w=0.01;

z=0.35;

thickness=input('thickness= ');

if thickness > t

pr=9-(x*(thickness-t))

ps=9.5-(y*(thickness-t))

ec=1.1-(w*(thickness-t))

epsf=32-(z*(thickness-t))

else pr=9+(x*(t-thickness))

ps=9.5+(y*(t-thickness))

ec=1.1+(w*(t-thickness))

epsf=32+(z*(t-thickness))

end

Appendix B

Atlas Code of the FeFET with Different Ferroelectric Thicknesses

go atlas simflags="-p 1"

```
# mesh and structure definition
#
mesh space.mult=1.0 outf=ferro1 1.str
x.m l=0 s=0.000578
x.m l=0.00144 s=0.000578
x.m l=0.00288 s=0.000568
x.m l=0.026 s=0.000289
x.m l=0.027 s=0.000289
x.m l=0.029 s=0.000578
#y.m l=-0.010225 s=0.00017
y.m l=-0.0158 s=0.00017
y.m l=-0.00029 s=0.000284
y.m 1=-0.0008 s=0.0025
y.m l=0.0 s=0.000114
v.m l=0.015 s=0.002273
eliminate y.dir y.min=0.00125 x.min=0.003125 x.max=0.028125
eliminate y.dir y.min=0.0025
region num=1 silicon y.min=0.0
region num=2 material=HfO2 y.max=0.0 y.min=-0.0008
region num=3 oxide y.max=-0.0008 y.min=-0.0158
#region num=4 oxide y.max=-0.01020 y.min=-0.010225
electrode num=1 material=NiSi name=source y.max=0.0 x.max=0.001444
electrode num=2 material=NiSi name=drain y.max=0.0 x.min=0.027444
electrode num=3 material=TiN name=gate top x.min=0.002889 x.max=0.026
electrode num=4 name=substrate bottom
```

doping uniform conc=1e17 p.type doping gaus conc=1e19 n.type x.right=0.004546 y.min=0 y.max=0.01 char=0.0008 doping gaus conc=1e19 n.type x.left=0.024454 y.min=0 y.max=0.01 char=0.0008

save outf=ferro1_1.str
tonyplot ferro1_1.str

#method newton autonr
method gummel newton itlim=4 trap maxtrap=2 vsatmod.inc=0.01 carriers=2
output con.band val.band band.param e.mobility h.mobility

```
solve init
solve vd=0.1
probe x=0 y=-0.0075 dir=90 polarization
# forward sweep
log outf=ferro1 2.log master
solve vgate=-7.0 vstep=0.01 vfinal=7.0 name=gate
# reverse sweep
material ferro.ec=-1.05e6
solve vstep=-0.01 vfinal=-7.0 name=gate
#Id-Vg plot
tonyplot -st ferro1_2.log -set ferro_1.set
```

```
# mesh and structure definition
#
mesh space.mult=1.0 outf=ferro2 1.str
x.m l=0 s=0.000578
x.m l=0.00144 s=0.000578
x.m 1=0.00288 s=0.000568
x.m l=0.026 s=0.000289
x.m l=0.027 s=0.000289
x.m l=0.029 s=0.000578
#y.m l=-0.010225 s=0.00017
y.m l=-0.0128 s=0.00017
y.m l=-0.00029 s=0.000284
v.m l=-0.0008 s=0.0025
v.m l=0.0 s=0.000114
y.m l=0.015 s=0.002273
```

```
eliminate y.dir y.min=0.00125 x.min=0.003125 x.max=0.028125
eliminate y.dir y.min=0.0025
```

```
region num=1 silicon y.min=0.0
region num=2 material=HfO2 y.max=0.0 y.min=-0.0008
region num=3 oxide y.max=-0.0008 y.min=-0.0128
#region num=4 oxide y.max=-0.01020 y.min=-0.010225
```

```
electrode num=1 material=NiSi name=source y.max=0.0 x.max=0.001444
electrode num=2 material=NiSi name=drain y.max=0.0 x.min=0.027444
electrode num=3 material=TiN name=gate top x.min=0.002889 x.max=0.026
electrode num=4 name=substrate bottom
```

doping uniform conc=1e17 p.type doping gaus conc=1e19 n.type x.right=0.004546 y.min=0 y.max=0.01 char=0.0008 doping gaus conc=1e19 n.type x.left=0.024454 y.min=0 y.max=0.01 char=0.0008

material region=3 ferro.ec=1.08e6 ferro.pr=8.3e-6 ferro.ps=8.7505e-6 ferro.epsf=31.3

save outf=ferro2_1.str tonyplot ferro2_1.str

```
solve init
solve vd=0.1
probe x=0 y=-0.006 dir=90 polarization
# forward sweep
log outf=ferro2 2.log master
solve vgate=-7.0 vstep=0.01 vfinal=7.0 name=gate
# reverse sweep
material ferro.ec=-1.08e6
solve vstep=-0.01 vfinal=-7.0 name=gate
#Id-Vg plot
tonyplot -st ferro2 2.log -set ferro 1.set
****
#####
go atlas simflags="-p 1"
# mesh and structure definition
```

x.m l=0.00288 s=0.000568 x.m l=0.026 s=0.000289 x.m l=0.027 s=0.000289 x.m l=0.029 s=0.000578

```
#y.m l=-0.010225 s=0.00017
y.m l=-0.01080 s=0.00017
y.m l=-0.00029 s=0.000284
y.m l=-0.00080 s=0.0025
y.m l=0.0 s=0.000114
y.m l=0.015 s=0.002273
```

eliminate y.dir y.min=0.00125 x.min=0.003125 x.max=0.028125 eliminate y.dir y.min=0.0025

region num=1 silicon y.min=0.0 region num=2 material=HfO2 y.max=0.0 y.min=-0.00080 region num=3 oxide y.max=-0.00080 y.min=-0.01080 #region num=4 oxide y.max=-0.01020 y.min=-0.010225

```
electrode num=1 material=NiSi name=source y.max=0.0 x.max=0.001444
electrode num=2 material=NiSi name=drain y.max=0.0 x.min=0.027444
electrode num=3 material=TiN name=gate top x.min=0.002889 x.max=0.026
electrode num=4 name=substrate bottom
```

```
doping uniform conc=1e17 p.type
doping gaus conc=1e19 n.type x.right=0.004546 y.min=0 y.max=0.01 char=0.0008
doping gaus conc=1e19 n.type x.left=0.024454 y.min=0 y.max=0.01 char=0.0008
```

```
save outf=ferro3_1.str
tonyplot ferro3_1.str
```

#method newton autonr method gummel newton itlim=20 trap maxtrap=10 vsatmod.inc=0.01 carriers=2 output con.band val.band band.param e.mobility h.mobility

```
solve init
solve vd=0.1
probe x=0 y=-0.005 dir=90 polarization
# forward sweep
log outf=ferro3 2.log master
solve vgate=-7.0 vstep=0.01 vfinal=7.0 name=gate
# reverse sweep
material ferro.ec=-1.1e6
solve vstep=-0.01 vfinal=-7.0 name=gate
#Id-Vg plot
tonyplot -st ferro3 2.log -set ferro 1.set
```

#####

```
go atlas simflags="-p 1"
```

```
#y.m l=-0.010225 s=0.00017
```

y.m l=-0.0088 s=0.00017 y.m l=-0.00029 s=0.000284 y.m l=-0.0008 s=0.0025 y.m l=0.0 s=0.000114 y.m l=0.015 s=0.002273

eliminate y.dir y.min=0.00125 x.min=0.003125 x.max=0.028125 eliminate y.dir y.min=0.0025

```
region num=1 silicon y.min=0.0
region num=2 material=HfO2 y.max=0.0 y.min=-0.0008
region num=3 oxide y.max=-0.0008 y.min=-0.0088
#region num=4 oxide y.max=-0.01020 y.min=-0.010225
```

```
electrode num=1 material=NiSi name=source y.max=0.0 x.max=0.001444
electrode num=2 material=NiSi name=drain y.max=0.0 x.min=0.027444
electrode num=3 material=TiN name=gate top x.min=0.002889 x.max=0.026
electrode num=4 name=substrate bottom
```

```
doping uniform conc=1e17 p.type
doping gaus conc=1e19 n.type x.right=0.004546 y.min=0 y.max=0.01 char=0.0008
doping gaus conc=1e19 n.type x.left=0.024454 y.min=0 y.max=0.01 char=0.0008
```

save outf=ferro4_1.str
tonyplot ferro4_1.str

obtaining Id - Vg characteristic

#method newton autonr

method gummel newton itlim=20 trap maxtrap=10 vsatmod.inc=0.01 carriers=2 output con.band val.band band.param e.mobility h.mobility

```
solve init
solve vd=0.1
probe x=0 y=-0.004 dir=90 polarization
# forward sweep
log outf=ferro4 2.log master
solve vgate=-7.0 vstep=0.01 vfinal=7.0 name=gate
# reverse sweep
material ferro.ec=-1.0e6
solve vstep=-0.01 vfinal=-7.0 name=gate
#Id-Vg plot
tonyplot -st ferro4_2.log -set ferro_1.set
#####
#####
tonyplot -overlay -st ferro1 2.log ferro2 2.log ferro3 2.log ferro4 2.log -set ferro 1.set
```

tonyplot -st ferro1_2.log -overlay ferro2_2.log -overlay ferro3_2.log -overlay ferro4_2.log -set ferro_1.set

quit

Appendix C

Atlas Code of the FeFET with Different Buffer Layer Thicknesses

go atlas simflags="-p 1"

```
y.m l=-0.00029 s=0.000284
```

```
y.m 1=-0.00080 s=0.0025
```

```
y.m l=0.0 s=0.000114
```

y.m l=0.015 s=0.002273

```
eliminate y.dir y.min=0.00125 x.min=0.003125 x.max=0.028125
eliminate y.dir y.min=0.0025
```

```
region num=1 silicon y.min=0.0
region num=2 material=HfO2 y.max=0.0 y.min=-0.00080
region num=3 oxide y.max=-0.00080 y.min=-0.01080
```

#region num=4 oxide y.max=-0.01020 y.min=-0.010225

electrode num=1 material=NiSi name=source y.max=0.0 x.max=0.001444 electrode num=2 material=NiSi name=drain y.max=0.0 x.min=0.027444 electrode num=3 material=TiN name=gate top x.min=0.002889 x.max=0.026 electrode num=4 name=substrate bottom

doping uniform conc=1e17 p.type doping gaus conc=1e19 n.type x.right=0.004546 y.min=0 y.max=0.01 char=0.0008 doping gaus conc=1e19 n.type x.left=0.024454 y.min=0 y.max=0.01 char=0.0008

save outf=ferro5_1.str
tonyplot ferro5_1.str

output con.band val.band band.param e.mobility h.mobility

```
solve init
solve vd=0.1
probe x=0 y=-0.005 dir=90 polarization
# forward sweep
log outf=ferro5 2.log master
solve vgate=-7.0 vstep=0.01 vfinal=7.0 name=gate
# reverse sweep
material ferro.ec=-1.1e6
solve vstep=-0.01 vfinal=-7.0 name=gate
#Id-Vg plot
tonyplot -st ferro5 2.log -set ferro 1.set
```

go atlas simflags="-p 1"

```
mesh space.mult=1.0 outf=ferro6_1.str
x.m l=0 s=0.000578
x.m l=0.00144 s=0.000578
x.m l=0.00288 s=0.000568
x.m l=0.026 s=0.000289
x.m l=0.027 s=0.000289
x.m l=0.029 s=0.000578
```

```
#y.m l=-0.010125 s=0.00017

y.m l=-0.01050 s=0.00017

y.m l=-0.00029 s=0.000284

y.m l=-0.00050 s=0.0025

y.m l=0.0 s=0.000114

y.m l=0.015 s=0.002273
```

eliminate y.dir y.min=0.00125 x.min=0.003125 x.max=0.028125 eliminate y.dir y.min=0.0025

region num=1 silicon y.min=0.0 region num=2 material=HfO2 y.max=0.0 y.min=-0.00050 region num=3 oxide y.max=-0.00050 y.min=-0.01050 #region num=4 oxide y.max=-0.01010 y.min=-0.010125

```
electrode num=1 material=NiSi name=source y.max=0.0 x.max=0.001444
electrode num=2 material=NiSi name=drain y.max=0.0 x.min=0.027444
electrode num=3 material=TiN name=gate top x.min=0.002889 x.max=0.026
electrode num=4 name=substrate bottom
```

```
doping uniform conc=1e17 p.type
doping gaus conc=1e19 n.type x.right=0.004546 y.min=0 y.max=0.01 char=0.0008
doping gaus conc=1e19 n.type x.left=0.024454 y.min=0 y.max=0.01 char=0.0008
```

contact num=3 material mun=800.0

```
save outf=ferro6_1.str
tonyplot ferro6_1.str
```

output con.band val.band band.param e.mobility h.mobility

```
go atlas simflags="-p 1"
```

```
# mesh and structure definition
```

#

```
mesh space.mult=1.0 outf=ferro7_1.str
x.m l=0 s=0.000578
x.m l=0.00144 s=0.000578
x.m l=0.00288 s=0.000568
x.m l=0.026 s=0.000289
x.m l=0.027 s=0.000289
x.m l=0.029 s=0.000578
```

```
#y.m l=-0.010125 s=0.00017
y.m l=-0.01 s=0.00017
#y.m l=-0.00029 s=0.000284
#y.m l=-0.00010 s=0.0025
```

y.m l=0.0 s=0.000114 y.m l=0.015 s=0.002273

eliminate y.dir y.min=0.00125 x.min=0.003125 x.max=0.028125 eliminate y.dir y.min=0.0025

```
region num=1 silicon y.min=0.0
#region num=2 material=HfO2 y.max=0.0 y.min=-0.00010
region num=2 oxide y.max=0.0 y.min=-0.01
#region num=4 oxide y.max=-0.01010 y.min=-0.010125
```

```
electrode num=1 material=NiSi name=source y.max=0.0 x.max=0.001444
electrode num=2 material=NiSi name=drain y.max=0.0 x.min=0.027444
electrode num=3 material=TiN name=gate top x.min=0.002889 x.max=0.026
electrode num=4 name=substrate bottom
```

doping uniform conc=1e17 p.type doping gaus conc=1e19 n.type x.right=0.004546 y.min=0 y.max=0.01 char=0.0008 doping gaus conc=1e19 n.type x.left=0.024454 y.min=0 y.max=0.01 char=0.0008

save outf=ferro7_1.str
tonyplot ferro7_1.str

```
solve init
solve vd=0.1
probe x=0 y=-0.005 dir=90 polarization
# forward sweep
log outf=ferro7 2.log master
solve vgate=-7.0 vstep=0.01 vfinal=7.0 name=gate
# reverse sweep
material ferro.ec=-1.1e6
solve vstep=-0.01 vfinal=-7.0 name=gate
#Id-Vg plot
tonyplot -st ferro7 2.log -set ferro 1.set
```

tonyplot -overlay -st ferro5_2.log ferro6_2.log ferro7_2.log -set ferro_1.set

tonyplot -st ferro5_2.log -overlay ferro6_2.log -overlay ferro7_2.log -set ferro_1.set

quit