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## Design, fabrication and implementation of a hash table processor

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*A Thesis*

*Design, fabrication and implementation  
of a hash table processor.*

*Rochester Institute of Technology  
Rochester N.Y.*

*A thesis, submitted to  
The Faculty of the School of Computer Science and Technology,  
in partial fulfillment of the requirements for the degree of  
Master of Science in Computer Science.*

July 04, 1987

Robert Paul Ketrick

Thesis Committee Approvals :

Dr. John Ellis (Advisor)

Dr. Peter G. Anderson

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## *Abstract*

### **Design of a hash table microprocessor** **By Robert P. Ketrick**

Hash tables have been used frequently to implement organized data table storage. However, there is a great deal of overhead in executing the hash algorithm every time the table is accessed. Alternatively, a content addressable memory (CAM) is a hardware implementation of an organized data table. A CAM requires very complex hardware design for each memory cell and therefore yields a very low cell density on each chip. This requires a large number of expensive chips to implement a large hash table.

In this thesis a simple hash function was designed into an integrated circuit using 4 micron NMOS technology. The scope of this thesis covers theoretical development, circuit design, simulation and fabrication. This chip performs a simple hashing algorithm using standard RAM to store the data and can interface to several 8-bit and 16-bit microprocessors.

The design of this device is aimed at improving the speed of compilers, assemblers, and whenever fast access to organized data tables are needed.

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## INTRODUCTION AND BACKGROUND

Since the dawn of computers the goal has always been to make them operate faster and more efficiently. Engineers, software designers and VLSI technology have been the major contributors to the effort of improving computing efficiency. Engineers have made great improvements in logic design. Software designers have greatly improved code writing techniques and together both have made tremendous progress in the area of design automation. In particular, the VLSI advances are responsible for increasing the complexity of the chips resulting in the improvement of speed and a chip size reduction.

However, increasing the processor speed is only one way the designer can improve the processing power of the computer. One of the biggest overheads in operating a computer system is the time spent storing and retrieving data from memory when the data is stored in a table format. In order to help in this area, the development of data management units known as CAMs (Content Addressable Memories) evolved, to store data based on its content rather than by assigning it a sequential address location. However, if a hardware CAM is not available,

then the table storage can be performed by a method implemented in software known as hashing.

The hashing algorithm is a process whereby the data associated with a variable is stored in a table based on some manipulation of the bit stream that makes up the variable name. This table is referred to as a hash table. A hash table is very useful in several types of systems. It can be especially advantageous in interpreted languages such as Basic or Lisp, as well as in assemblers, compilers, data base management or whenever data must be stored in a table format where fast storage and retrieval is necessary.

### Problem Statement

The problem is to design and implement an Integrated Circuit that will perform a simple hashing function. The objective of this is to show how a software based hashing function can be implemented in hardware. This will support a novel view of CAMs and show how the

device can be implemented into a system to improve the efficiency of a compiler or an assembler.

The integrated circuit is designed to function with several different  $\mu$ P's, both 16-bit and 8-bit machines. The proposed system is a 16-Bit machine which will have a speed advantage over the 8-bit  $\mu$ P's. This speed advantage results from the 8-bit  $\mu$ P's having to perform two writes to the PIA (Peripheral Interface Adaptor) before the data can be loaded to the 16-bit data bus of the HTIC.

The HTIC has two large blocks of isolated memory that are used as a storage table. One block is for the key values (32-Bits wide) and the second block is for the data values (16-Bits) associated with each key. The 16-bit data values are used as pointers. When a value is stored into the table, its corresponding variable name is stored along with it. This is where this memory scheme gets its name Associative Memory. The data is stored in association with its variable name.

### Previous Work



Hashing may be thought of as a software implementation of a CAM. However, hashing algorithms generate a lot of overhead since the hashing routine must be run everytime there is an access into the hash table. Traditional CAMs have a drawback, in that they require special hardware to be designed into each memory cell in order to function, thereby producing a very low yield of memory cells per unit area. Our HTIC (Hash Table Integrated Circuit) is a hardware implementation of a simple but fast hashing algorithm which incorporates most of the software overhead from the CPU. The HTIC can be interfaced to conventional RAM which requires that no special hardware be designed into each memory cell and therefore makes this implementation more cost effective. This arrangement is a cross between the two standard implementations of table addressing.

The development of CAMs started during the mid 1950's. There are two implementations of content addressing. One uses a data dependent memory mapping implemented by pure programming techniques; the second one uses special hardware in memory cells to store and retrieve data items. Both principles were developed simultaneously, about 1955.<sup>1</sup>

## ***Content Addressable Memories***

The basis for our HTIC lies in the concept of content addressable memories (CAMs). A content addressable memory is a memory system that searches for data on the basis of their content rather than on the basis of their location.<sup>2</sup> This basically means that CAMs are a way of storing data in an ordered manner, much like alphabetizing.

Since content addressable memories require a great deal of special hardware associated with each memory cell in order to perform parallel reading of all cells, only a few thousand cells may be constructed on a single chip; <sup>3</sup> therefore very little information can be stored in one CAM chip. However, CAMs hold an advantage in that a readout operation can be accomplished in one cycle due to the CAMs ability to compare all locations in parallel. Some CAM's allow the ability to do partial key matching or range checking. These devices require even more special logic for each cell.

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<sup>2</sup> Content-Addressable Memories , T. Kohonen, pg. 6

<sup>3</sup> Content-Addressable Memories , T. Kohonen, pg. 1

## *Hashing*

Hashing is an alternative method of organized table storage. A key is used to place data into the table. The key is a tag that is associated with each data. In many cases the key is the actual variable name of the data being processed. Implementation is accomplished with pure programming techniques. Hence, everytime the hash table is accessed the hashing algorithm must be executed in order to store or retrieve the data.

Hashing can serve as a very fast method of storage and retrieval providing that the key and data are always in the same format. The domain of keys in a system is referred to as the data space and the domain of all memory locations is referred to as the address space. <sup>+</sup> Therefore, hashing can be viewed as mapping the data space to the address space.

Hashing is done by applying an algorithm to the key in order to obtain an address within the available memory to store the data. The same algorithm must be applied

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<sup>+</sup> Associative Memory , T. Kohonen, pp. 13 - 15.

<sup>+</sup> Content-Addressable Memories , T. Kohonen, pg. 40

during recall in order to retrieve the data.

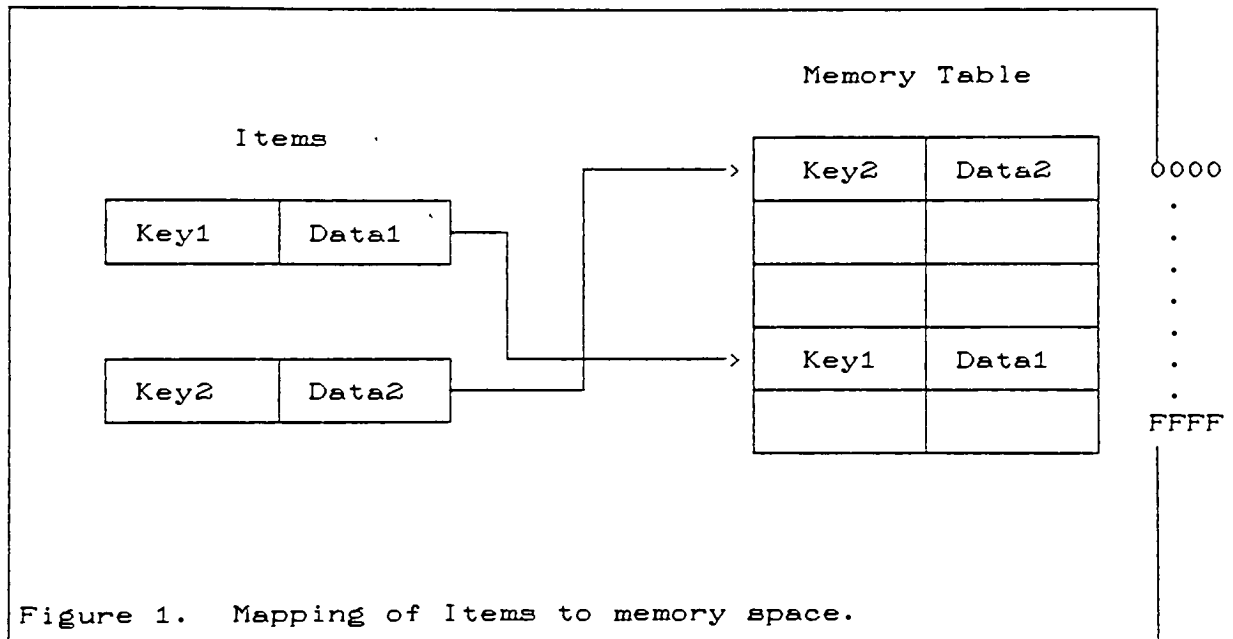
The hashing algorithm implemented in this thesis works as follows. We first form an address from the key by using a function  $f(\text{key})$ . This address is the initial probe into the hash table. Once the address is formed the contents of the location pointed to by the result of  $f(\text{key})$  will be examined. If the location is empty then we are free to store the key and data there. If the location is used and equal to the key that we are looking for, then we may either read the data associated with the key or may overwrite the existing data value. If the location is not empty and not equal to the key we are looking for, then we must form a new address based on the current address with the addition of some offset. The offset can be chosen in several ways : (1) add 1, called linear rehash; (2) add  $k$  to the  $k$ th collision, called quadratic rehash; or (3) add  $g(\text{key})$ , called random rehash. The recalculation method chosen in this thesis is random rehashing. This rehashing continues until an empty location is found or the key is matched.

Since the hashing algorithm relies on the knowledge of which memory locations are filled when it selects a location to place data into the table, removing an entry once put into the table entails additional complexity

# Hash Table Processor

## A Thesis

that we have chosen not to include in this project. If any entries were removed from the table then we would lose the ability to retrieve many of the keys that have already been stored. Locations that were previously written to and caused the hash algorithm to rehash over the used location would now appear empty. Therefore, once a key is put into the table it must remain until the application has finished and the table can be reinitialized for another run.



*Uses of hashing and hash tables.*

## Hash Table Processor A Thesis

One of the first applications of a hash table was the IBM assembler (1954). It used a hash table to set up and keep track of the symbols used during the assembler's execution. Each symbol was assigned a value in the table and that value represented the symbol's address for conversion to object code.

In recent years, practically all symbol tables for assemblers and compilers are implemented with the use of a hash table. Symbol tables are accessed frequently and in an unpredictable order during compilation and hash coding has proven most efficient in maintaining them.

Furthermore, the use of hash tables can be extended to the area of data base management, especially in multiple key word searching operations. One can see from this how useful a hash table processor can be to these types of applications.

Theoretical and Conceptual Development

*Principles of hash coding.*

The focus of hash coding is to map all possible data into the available address space with as uniform a distribution as possible in order to minimize search times. This is done in two steps. First, the keyword must be converted to a numeric form, then the numeric form must be mapped to the address space. This is accomplished by creating a hash function,  $f(x)$ . This function is used to create an address for each key:  $Address = f(key1)$ . Ideally, we would like our hashing function,  $f(x)$ , to generate a unique address that is uniformly distributed throughout the entire address space for every key value in the data space. That is, we would like  $f(key1) \neq f(key2)$  for all values of  $key1$  and  $key2$  not equal to each other. This would insure a one cycle operation for both reads and writes. However, since the data space is usually much larger than the address space, with every hash function there exists a finite, nonzero probability that  $f(key1) = f(key2)$ , where  $key1 \neq key2$ , for some values of  $key1$  and  $key2$  that exist in the

data space.<sup>5</sup>

The condition  $f(\text{key1}) = f(\text{key2})$  is called a conflict or collision. We will refer to the nonzero probability,  $P(c)$ , as the probability of a collision occurring. If we choose a good hash function then  $P(c)$  will be low because our distribution will be close to uniform.

Since only one item is allowed to occupy any one location, our hashing algorithm must have some method of dealing with this problem. Kohonen<sup>6</sup> suggests adding one to the address until an empty location is found, this is called linear hashing. Once a collision occurs and we begin using the rehash function, we must mark each location after it has been used so that the rehash of a key does not overwrite an already existing entry in the table. One way to solve this is to add an extra bit to each location and set the bit when a location has been used.

Upon retrieval there is a problem in identifying which value of the hashed or rehashed address the data belongs to. Since  $P(c)$  does exist, we must have a positive way of

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<sup>5</sup> Content-Addressable Memories , T. Kohonen, pg. 56

<sup>6</sup> Content-Addressable Memories , T. Kohonen, pg. 40



## Hash Table Processor A Thesis

identifying which data goes with which key. As shown in Figure 1 on page 15, a solution to this is to set aside a portion of memory location to store the actual key or some unique function  $f'(key)$ . Now, when we probe into the table we can look at the contents of the key portion of the addressed location to determine if it is in fact the location that we are looking for. If it is, then our search is done. Otherwise, we must rehash and probe into another location until we find the location that we want.

### *Theoretical design of a hash function*

The key used for this design is comprised of a bit stream 32 bits wide, the equivalent of four ASCII characters. Since we have no knowledge of the distribution of the data we assume that it has a uniform distribution. Therefore, we conclude that if we choose the odd bits or the even bits for our initial probe, we will get a uniform distribution. Hence, we will choose all the odd bits from the bit stream thereby creating a 16-bit address pointer into the hash table and a hash table size of 64K locations. However, as stated previously, every hash function needs a method of dealing with collisions. Therefore, we need some kind of increment or offset to add to the original address value.

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Our increment for this function will be all the even bits of the bit vector and is therefore independent of the initial probe. The least significant bit of the increment is forced to a logical "1" and therefore forces the increment to be odd. When memory size is a power of 2, and the increment is odd, the set of probed addresses  $\{(n * \text{increment}) \bmod (\text{memory size})\}$  is a permutation of all addresses of the memory; we therefore guarantee to probe the entire memory. Furthermore, experience has shown that it is almost impossible to do this wrong.<sup>7</sup>

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<sup>7</sup> Peter G. Anderson, Committee member, private correspondence

# Hash Table Processor

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### PROJECT DESCRIPTION

The objective of this thesis is to design and analyze the performance of a specialized hash table processor. The circuit is designed as a hash table coprocessor unit that may be added to a system much like a math coprocessor is added for floating point operations. The chip is used as a memory mapped I/O device. The main CPU can use the device by issuing reads and writes to it. The CPU must also have an interrupt available in order to use this device. When the device completes processing a request it activates an interrupt request, similar to an I/O device.

### Functional Specifications

The HTIC is a 64-pin DIP fabricated using 4 micron NMOS VLSI technology. The pinout for this chip is shown in Figure 2 on page 31. The definition of the I/O is as follows :

<i>GND</i>	Ground (0 Volts)
<i>Vdd</i>	+5 Volts
<i>Ap0 - Ap15</i>	Address Pointer lines 0 to 15. These lines are used to locate data in the hash table. When the HTIC probes into the table, the contents of the HREG are placed onto these

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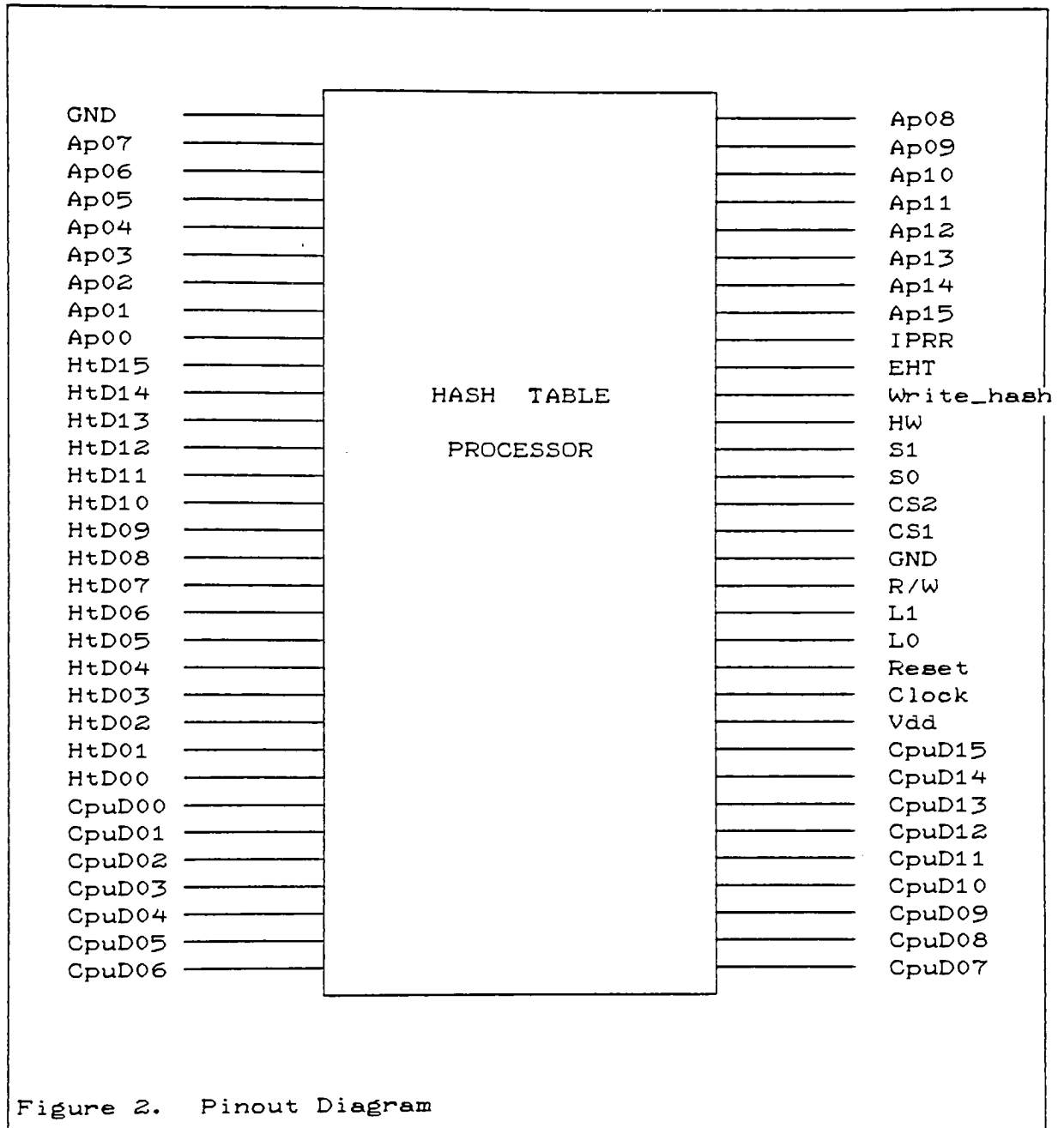
address lines. These lines are held until the IC generates another address pointer.

<i>HtD0 - HtD15</i>	Hash Table Data Lines. These data lines access the contents of the key table. They are isolated from the data lines of the CPU in the system.
<i>CpuD0 - CpuD15</i>	CPU Data Lines. These data lines connect directly to the hosts CPU's data bus and are the means by which the key value gets passed to the chip.
<i>S0 and S1</i>	Status 0 and Status 1 lines. There are three different types of status that the chip can return for any request: found, not found or empty. These status lines are read by the CPU after the HTIC has issued an interrupt request. See Figure 3 on page 32 for state definitions.
<i>L0 and L1</i>	Load 0 and Load 1 lines. These are sourced by the CPU and are used to instruct the chip which register to load. See Figure 4 on page 32 for the state definitions.
<i>IPRR</i>	Interrupt Processor Result Ready. This line is active low and indicates to the CPU that the HTIC has finished processing the given data and is now ready to process the next key.
<i>EHT</i>	Enable Hash Table. This line is sourced by the HTIC and acts as a chip select to the hash data table. It is activated when the HTIC is reading or writing to the table. This line is active high.
<i>Write_Hash</i>	Write Hash line. This line is sourced by the Hash HTIC and is the read/write line to the hash data table. Write is active low and is delayed internally by 1/2 cycle (about 200 ns.) in order to create enough setup time for the RAM.
<i>HW</i>	High Word enable line. This line is sourced by the HTIC and determines which byte of the key will be written into the data table. The most significant word is written when the line is high and the least significant word is written when the line is low.

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<b><i>CS1, CS2</i></b>	Chip Selects 1 and 2. These lines are sourced by the host CPU and when selected will activate the HTIC. CS1 is active low and CS2 is active high.
<b><i>R/W</i></b>	Cpu Read/Write line. This line is sourced by the CPU and is the read/write line from the CPU.
<b><i>Reset</i></b>	This is a state reset line only, not a master reset. Since all internal registers must be initialized before the HTIC can function, only a state reset is needed. This pin is used to break the HTIC out of the rehashing loop. This pin must be activated via external logic. Activating this pin will not destroy the contents of any of the internal registers.
<b><i>Clock</i></b>	Clock input. This is the clock input to the chip. A 2.5 Mhz crystal will be driving the input. All internal clocks will be generated from this input.

# Hash Table Processor A Thesis



# Hash Table Processor A Thesis

S0	S1	Definition
0	0	Key not found in table
0	1	Key found in table
1	0	Location probed is empty
1	1	Undefined state

Figure 3. State Definition of S0 and S1

L0	L1	Definition
0	0	Load Key Memory Register 1
0	1	Load Key Memory Register 2
1	0	Load Empty Register
1	1	Write the new key into table

Figure 4. State Definition of L0 and L1

Note: The case of writing a new key is only valid if the HTIC has found an empty location.

The bit naming convention will be as follows :

MSB

LSB

b31, b30, b29, ..... b3, b2, b1, b0

These 32 bits correlate to the 4 ASCII characters that

## Hash Table Processor A Thesis

represent the key being processed.

### Internal Architecture

The device consists of five internal 16-bit data registers, a carry chain ALU to perform the rehashing computation, a PLA (Programmable Logic Array) to generate the microcode for the hash table processor algorithm and a 16-bit comparator to compare hash table entries with the contents of the internal data registers. The diagram of the internal data path is shown in Figure 5 on page 36. The internal registers are defined as follows: key memory register #1 (KMR1), key memory register #2 (KMR2), empty register (EREG), delta register (DREG) and a hash register (HREG). The KMR1 and KMR2 hold the data passed to the chip from the host  $\mu$ P. This data is the ASCII representation of the characters that form the key being processed. KMR1 holds the most significant word and KMR2 holds the least significant word. The EREG holds a user defined value that is used to flag an empty location in the hash table. This value is written to all locations during the initialization phase on the device. After the KMR1 and KMR2 are loaded, the hashing network loads the DREG with the even bits of the key and the HREG with the odd bits per specification of



Hash Table Processor  
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the hashing algorithm. Once this has been accomplished, the HREG and DREG look like:

HREG

b31	b29	b27	....	b5	b3	b1
-----	-----	-----	------	----	----	----

DREG

b30	b28	b26	....	b4	b2	0
-----	-----	-----	------	----	----	---

The data bus is split into three parts. The top consists of a 16-bit comparator. The middle section consists of three 16-bit registers, KMR1, KMR2 and EREG. The bottom section of the data bus consists of the bus driver, hash network, delta register, 16-bit carry chain adder and the hash register.

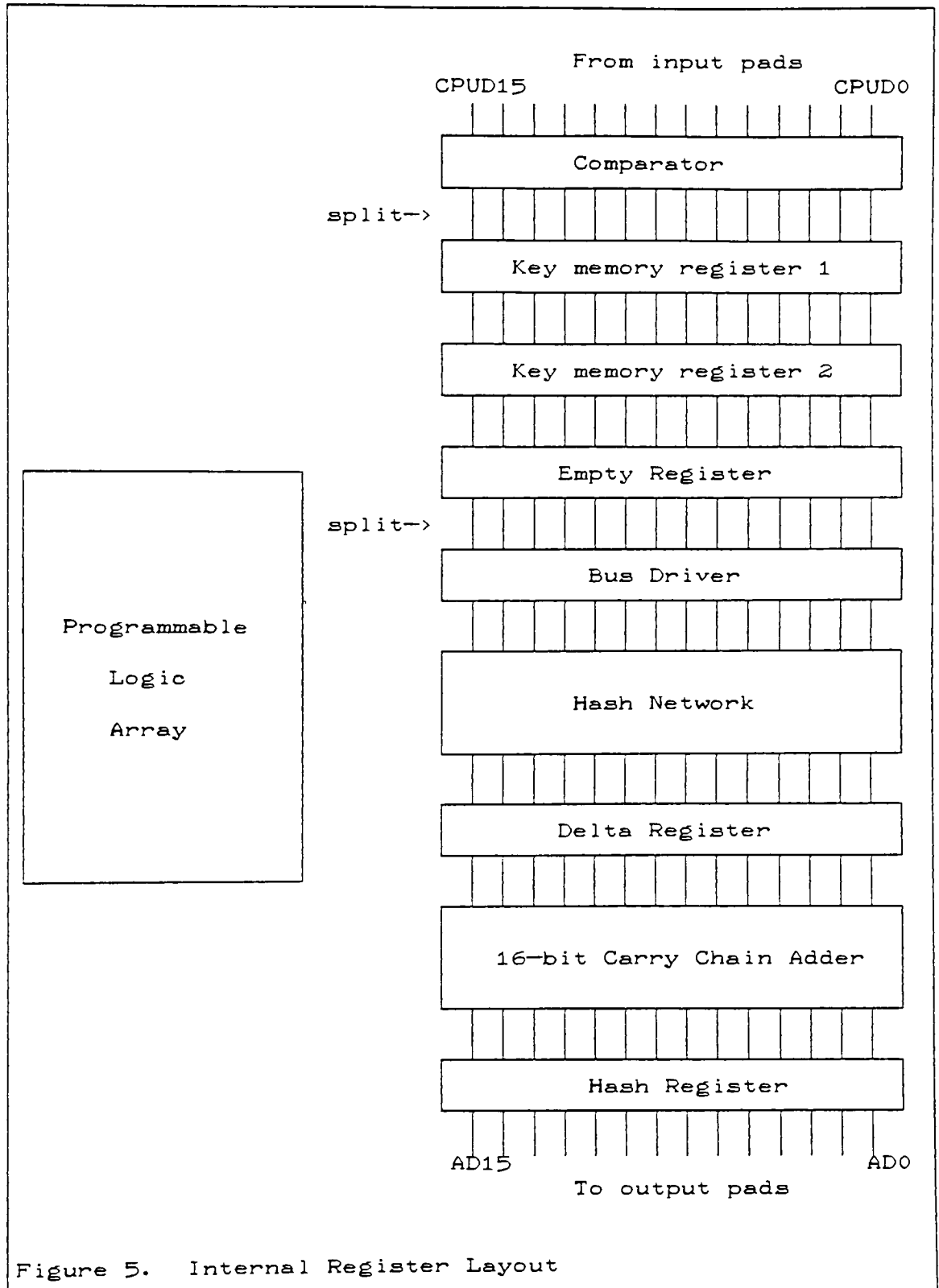
The comparator is split off only when the chip is comparing the hash table data to the internal registers. During loading of the internal registers, the comparator is not split from the middle section of the bus. The middle section of the bus is always precharged to +5 volts during  $\frac{1}{2}$  of the clock cycle. This design uses a two phase non-overlapping clock scheme. During  $\frac{1}{2}$  of the clock cycle registers may be written or read. During  $\frac{1}{2}$  of the clock cycle, all registers are refreshed and the data bus is

## Hash Table Processor A Thesis

precharged to +5 volts. The data registers cannot be accessed during  $\phi_2$ . Precharging is accomplished by connecting the data bus directly to the +5 volt bus during the  $\phi_2$  clock cycle. Precharging is advantageous because of the circuit characteristics. The data bus is a large piece of diffusion which takes a long time to pull up to +5 volts due to its large capacitance. Furthermore, the time for the pullup transistor to charge the bus relative to the time that it takes the pulldown transistor to discharge the data bus is significantly greater. (See Figure 6 on page 37 for diagram of pullup and pulldown transistors.) Therefore, to increase the maximum speed of operation, precharging is used.

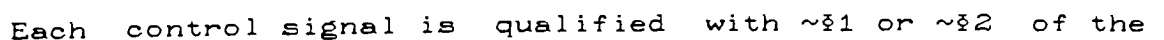
The bus driver is a set of 16 super buffers used to maximize the current drive through the long lines of diffusion in the hash network. The hash network manipulates the data from the KMR1 and KMR2 to form the HREG and DREG. The least significant bit of the DREG is grounded and the Carry\_in\_0 on the ALU is set to +5 volts to insure that the increment is always odd.

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The design of the internal data registers is shown in

Figure 6 on page 37. Each bit of the register consists of a pair of inverters. During phase two (#2) of the clock cycle the output of each inverter pair is fed back to the input thereby causing each cell to refresh itself. Each cell is also connected to the data bus by two pass transistors. One for writing and the other for reading the register. Both pass transistors have control signals attached to their gates.



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non-overlapping clock. This is to insure that all register operations occur on the proper clock phase.

### Functional Description

The chip is first reset to put its PLA into a known state. Then the EREG must be set to some value in an initialization sequence before the chip is ready to function. The initialization sequence is as follows. The user must first write 0000h to KMR1, this is to give the HTIC an initial location to start writing the empty value into the hash table (i.e., location 0000h to initialize the entire table). Then the host CPU must write the EREG with the value that has been selected to represent an empty location in the key table. Once the EREG has been written, this will trigger the state machine to start writing the value of the empty register into the hash table. The HTIC stays in a loop incrementing the address pointer by one and writing the value of the EREG into the table until Carry\_out\_15 equals one, thereby initializing the entire table.

The user must write the most significant word of the key value to KMR1 then write the least significant word to

## Hash Table Processor A Thesis

KMR2. Once the KMR2 has been written, the chip will start processing the given key.

Next, the PLA will gate off the input pads and begin performing the hash function. The hash function takes 4 machine states to load the HREG and DREG. During the first state, KMR1 is gated onto the internal data bus and the hashing network writes the odd bits of this register into the lower 8 bits of the HREG. During the second state of this operation, the contents of KMR2 are gated onto the bus and loaded into the upper 8 bits of the HREG. This process is repeated to load the DREG with the even bits of the key value.

Once the chip is loaded, the first address that will be pointed to by the HTIC will consist of a concatenation of  $b_{31}, b_{29}, b_{27}, b_{25}, \dots, b_5, b_3, b_1$  from the original key. At this point we obtain the first address pointer by placing the contents of the HREG onto the address pointer lines (AP0-AP15) and strobing the Enable Hash Table (EHT) line active.

The key portion of this location is examined by the 16-bit comparator to test for equality. Once the contents of the key location have been determined, there are three possible cases that may occur. The location is either equal, not equal or empty. If the location is equal, this

## Hash Table Processor A Thesis

means the HTIC has found the location that it is looking for. If the location is not equal, the HTIC will perform a rehash function, look into the table again and repeat this process until the RESET line is strobed low. Thereby, breaking the PLA out of the rehash loop and returning the HTIC to state zero. If the location is empty, then the HTIC will interrupt the host CPU and tell it that it has found an empty location. When this occurs, the host CPU will determine what action must be taken. This is detailed in the "System application for HTIC" on page 56.

The rehash function is accomplished by adding the DREG to the HREG and placing the result back into the HREG. The ALU (Arithmetic Logic Unit) that is used is a 16-bit carry chain adder and the overflow is thrown away.

### Limitations and Restrictions

The system's limitation is mainly in the speed at which the chip can function. The faster the chip can run the better the system's efficiency will be.

The number of probes into the table must be limited by some MSI logic around the HTIC in order to break it out of

## Hash Table Processor A Thesis

the loop that the state machine enters once rehashing begins. This MSI (Medium Scale Integration) logic can consist of a binary counter and an AND gate. When the counter overflows, it will activate an interrupt line to tell the CPU that it has finished. Since the Status lines will read "Not Found" the CPU will simply think the entry is not present in the hash table. This is not to be confused with the case of writing data to the hash table. If data is to be written, there must be an empty location or the entry must be found within the specified number of probes.

### Problems encountered

There were several things that could have been done better. There were a great deal of chip design errors. Many of these are attributed to the lack of complete simulation and modeling done before the actual layout of the device began. There was a sufficient amount of simulation for the bit slices of the device and for the complete data path. However, the major downfall was in the lack of simulation of the complete device; that is the data path, the PLA, and the I/O pads together. Simulation proved to be very valuable in the places where it was used and at



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the same time hurt the design effort in the places that it was not used.

There were also problems in that several things had to be designed into the chip as the design effort progressed. This was due to an incomplete design specification at the beginning of the design effort. During this project, the specifications, modeling and layout of the device all took place concurrently. In actuality, the specification should have been completed first, followed by the design being modeled. In modeling the design, any updates to the specification found from modeling should be incorporated into the specifications. Once the model works and the specifications are up to date, then the actual layout should begin.

At the end of the layout effort a problem was encountered. This problem is known as simultaneous switching. It occurs when a device has a large percentage of its outputs changing from a logical 1 to a logical 0. If too many outputs change at the same time the chip can not sink all the current from the I/O pads. When this occurs the current across the ground wire induces a large voltage and raises the voltage level of ground as high as +3.5V to +4.0V thereby actually shutting down the chip and causing it to fail. The way to fix this problem is to use more than one ground pin to distribute the current surge. This

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will reduce the voltage induced across the ground wires. Therefore, the CS0 pin was tied to the ground rail and its input pad was changed to a second ground pin in order to distribute the current flow inside the chip.

There are three known problems in the current chip. One is that the PLA only checks the high word when it is testing for equality to the empty value. The second is that the IC needs external logic to break the device out of its rehashing loop. Third, the LSB of the DREG has power connected to it. None are significant problems and could be easily removed in the next release of this device if one were to be designed.

The simulation speed of the device was evaluated to be 2.5 Mhz before the device began to fail. This speed is not fast enough to show any great benefit from using this device. However, if the speed were say 100 Mhz (10 times the speed of the CPU), then even at very high table densities the store or retrieve operations would be done very quickly. In order to improve the speed of this device, it would have to be redesigned in CMOS and use smaller demensions, maybe 1 or 2 microns, for the chip layout.

## TEST PLAN AND STATISTICAL DATA

The following sections define the specifications for the test plan and actual procedures that were used in the testing of this device. In the following test descriptions the word "will" implies that this is a logical state or sequence leading to the test condition. The word "should" implies that if the circuit behaves as the statement describes, then the requirement is fulfilled. All simulation requirements were fulfilled before the HTIC was released for fabrication.

### Simulation Tests and Requirements

**Test Number :** 1

**Requirement :** The HTIC's state machine must return to state 0, the idle state, following a reset.

**Description :** The simulation will be started and the RESET line will be set to a logical 0 (its active state). The state machine should go to state 0 and stay there.

**Test Number :** 2

**Requirement :** The HTIC's KMR1 can be loaded by using the L0 & L1 control lines.

**Description :** The RESET line will be enabled and the HTIC will be set to state 0. The chip will be selected and the R/W line will be set low. Data will be placed on the CPU Data lines. L0 & L1 will be set low to load KMR1. The internal register will be monitored and the data should appear one (1) clock cycle later.

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**Test Number :** 3

**Requirement :** The loading of KMR2 will start the IC into its hashing algorithm and probing the hash table.

**Description :** The RESET line will be enabled and the HTIC will be set to state 0. The chip will be selected and data will be written to KMR2. The state machine should go to state 4 and perform the hash function on the data. Once the hash function is done, the chip should place a valid address on the AP0-AP15 lines and enable the hash table.

**Test Number :** 4

**Requirement :** The HTIC will perform the proper hash function.

**Description :** There will be several cases run for this test. In every case, the first address produced by the HTIC should be all the odd bits in the 32 bit key given to the HTIC. Every address thereafter should be the previous address plus the even bits with the LSB of the offset set to '1'. This test will also verify that the ALU is functioning properly.

**Test Number :** 5

**Requirement :** If a key is not found within a specific number of probes, the state machine shall abort the search via an external RESET sourced by the GLUE logic.

**Description :** The KMR1 and KMR2 will be loaded. The HTIC will be allowed to function for several rehash cycles. Then the RESET line will be pulled down and the state machine should go to the state 0, the idle state. Status lines 0 and 1 should read S0 = 0, S1 = 0.

**Test Number :** 6

**Requirement :** If the Key is found the rehash algorithm is stopped and the HTIC notifies the host CPU via the interrupt line that the HTIC is done

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and the status lines have the proper status.

*Description :* The KMR1 and KMR2 will be loaded and the HTIC will be allowed to calculate its first address. Next, data will be placed on the Hash Table Data lines that is equal to the contents of KMR1 and on the next cycle the data equaling the contents KMR2 will be placed on the Hash Table Data lines. At this point, the HTIC should think that it has found the location that it is looking for. The HTIC should interrupt the host CPU and return a status of found (S0 = 0, S1 = 1).

*Test Number :* 7

*Requirement :* When an empty location is probed the HTIC will stop processing and inform the host CPU that it has encountered an empty location.

*Description :* The KMR1 and KMR2 will be loaded and the HTIC will be allowed to function. At the time that the HTIC is making its first probe into the hash table, data representing the programmed 'Empty Value' will be placed on the data bus. The HTIC should think that it has encountered an empty location and report this to the host CPU via interrupting it and posting 'Location Empty' status on the status line (S0 = 1, S1 = 0).

*Test Number :* 8

*Requirement :* Load the Empty register and initialize the entire hash table.

*Description :* The KMR1 will be loaded with 0000h as the starting address for the hash processor to begin initializing. Then the EREG will be written with 8000h. The chip will be allowed to function and it should write all 64K locations with the value stored in the EREG and interrupt the host CPU when it has finished.

Programs Written

There have been two programs written to simulate this device. One written in 'C' which simulates the hash table processor functioning in a system. The source code for this can be found in appendix B. The second program is a model of the HTIC and was simulated on the RITCV computer system at RIT before the chip layout was started. The layout of the chip was simulated to insure that it matches the original logic of the circuit.

Statistical analysis of the hash function.

The program written in C that simulates the hash function shows that it is a good hash function. The program simulates the hash processor trying to store 64K keys into the hash table. Some limitations were put on the simulation so that it could finish running. If the entry was already in the table then the second appearance of the key was thrown out of the data sample and the first entry was left in the table. Once the table reaches 98% full the simulation is ended.

Samples were taken every 1K entries that were put into

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the table. Listed below are the results from one of the simulation runs. The simulation was run with six (6) different sets of data and all results were consistent. The input data for these simulations was generated from a random character string generator (Appendix C for source code). All bit patterns are considered legal except for the string "\*\*\*\*" which is reserved to represent the empty string or location. The collision density table shows the collision distribution for each 1K set of table entries. The table reads as follows: In the first 1K table entries, 997 keys were placed into the table with no collisions, 26 entries had 1 collision and 1 entry had 2 collisions.

Initializing table, please wait .... Done.

Total collisions = 28 , # of entries = 1024

1.5625% full, average # of collisions = 0.0273.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	997	26	1	0	0	0	0	0	0	0	0

Maximum collisions = 3

Total collisions = 104 , # of entries = 2048

3.1250% full, average # of collisions = 0.0508.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	958	57	8	1	0	0	0	0	0	0	0

Maximum collisions = 4

Total collisions = 257 , # of entries = 3072

4.6876% full, average # of collisions = 0.0837.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	891	115	17	0	1	0	0	0	0	0	0

Total collisions = 449 , # of entries = 4096

6.2501% full, average # of collisions = 0.1096.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	852	155	14	3	0	0	0	0	0	0	0

Total collisions = 677 , # of entries = 5120

7.8126% full, average # of collisions = 0.1322.

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Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
825 174 22 2 1 0 0 0 0 0 0

Total collisions = 994 , # of entries = 6144  
9.3751% full, average # of collisions = 0.1618.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
750 237 32 4 1 0 0 0 0 0 0

Maximum collisions = 5

Total collisions = 1405 , # of entries = 7168  
10.9377% full, average # of collisions = 0.1960.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
683 282 50 8 0 1 0 0 0 0 0

Total collisions = 1845 , # of entries = 8192  
12.5002% full, average # of collisions = 0.2252.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
689 252 65 14 4 0 0 0 0 0 0

Maximum collisions = 6

Total collisions = 2399 , # of entries = 9216  
14.0627% full, average # of collisions = 0.2603.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
625 288 80 21 8 1 1 0 0 0 0

Maximum collisions = 7

Total collisions = 3105 , # of entries = 10240  
15.6252% full, average # of collisions = 0.3032.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
551 319 103 35 10 3 0 3 0 0 0

Maximum collisions = 10

Total collisions = 3971 , # of entries = 11264  
17.1878% full, average # of collisions = 0.3525.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
462 352 147 46 11 3 1 1 0 0 1

Maximum collisions = 13

Total collisions = 4903 , # of entries = 12288  
18.7503% full, average # of collisions = 0.3990.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
447 348 156 47 17 3 1 3 1 0 1

Total collisions = 5645 , # of entries = 13312  
20.3128% full, average # of collisions = 0.4241.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
561 287 114 37 15 6 2 2 0 0 0

Total collisions = 6585 , # of entries = 14336  
21.8753% full, average # of collisions = 0.4593.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
477 306 152 60 13 9 3 1 1 1 1



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Total collisions = 7495 , # of entries = 15360

23.4379% full, average # of collisions = 0.4880.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
480 313 146 56 19 4 4 1 0 0 1

Total collisions = 8710 , # of entries = 16384

25.0004% full, average # of collisions = 0.5316.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
414 297 152 92 37 18 8 2 2 1 1

Maximum collisions = 16

Total collisions = 9820 , # of entries = 17408

26.5629% full, average # of collisions = 0.5641.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
425 292 201 70 20 3 5 2 2 0 4

Total collisions = 11192 , # of entries = 18432

28.1254% full, average # of collisions = 0.6072.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
351 295 212 95 35 15 10 6 2 1 2

Maximum collisions = 17

Maximum collisions = 18

Total collisions = 12990 , # of entries = 19456

29.6880% full, average # of collisions = 0.6677.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
266 287 230 121 53 25 15 8 5 4 10

Total collisions = 14597 , # of entries = 20480

31.2505% full, average # of collisions = 0.7127.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
332 269 206 107 50 27 12 8 4 3 6

Total collisions = 16081 , # of entries = 21504

32.8130% full, average # of collisions = 0.7478.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
445 204 170 91 52 16 13 12 5 6 10

Maximum collisions = 27

Total collisions = 17837 , # of entries = 22528

34.3755% full, average # of collisions = 0.7918.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
262 297 241 103 51 33 17 10 2 0 8

Total collisions = 19892 , # of entries = 23552

35.9380% full, average # of collisions = 0.8446.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
257 247 210 142 79 35 23 5 6 6 14

Maximum collisions = 36

Total collisions = 22165 , # of entries = 24576

37.5006% full, average # of collisions = 0.9019.

Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
279 208 232 123 62 38 20 17 12 10 23

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Total collisions = 24330 , # of entries = 25600  
 39.0631% full, average # of collisions = 0.9504.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
                           299 238 179 114 82 33 27 14 3 12 23  
 Maximum collisions = 66

Total collisions = 26957 , # of entries = 26624  
 40.6256% full, average # of collisions = 1.0125.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
                           167 215 227 179 97 55 28 19 7 9 21

Total collisions = 29505 , # of entries = 27648  
 42.1881% full, average # of collisions = 1.0672.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
                           177 223 260 162 84 40 24 8 15 7 24

Total collisions = 32132 , # of entries = 28672  
 43.7507% full, average # of collisions = 1.1207.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           192 189 245 167 104 51 29 9 9 6 23

Total collisions = 33952 , # of entries = 29696  
 45.3132% full, average # of collisions = 1.1433.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           390 216 149 107 70 36 14 10 8 6 18

Total collisions = 37422 , # of entries = 30720  
 46.8757% full, average # of collisions = 1.2182.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           168 143 205 146 102 81 55 37 15 13 59

Total collisions = 41360 , # of entries = 31744  
 48.4382% full, average # of collisions = 1.3029.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
                           99 130 215 182 132 84 50 33 19 14 66

Total collisions = 45327 , # of entries = 32768  
 50.0008% full, average # of collisions = 1.3833.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10-  
                           154 128 174 156 133 71 51 35 30 22 70

Total collisions = 49067 , # of entries = 33792  
 51.5633% full, average # of collisions = 1.4520.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           175 144 156 162 126 72 59 37 15 12 66

Total collisions = 52572 , # of entries = 34816  
 53.1258% full, average # of collisions = 1.5100.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           220 128 151 163 122 63 43 32 26 17 59

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Maximum collisions = 82

Total collisions = 57597 , # of entries = 35840

54.6883% full, average # of collisions = 1.6071.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	96	95	152	164	149	96	68	40	33	24	107

Total collisions = 62514 , # of entries = 36864

56.2509% full, average # of collisions = 1.6958.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	104	84	140	164	135	122	70	51	22	17	115

Maximum collisions = 181

Total collisions = 67573 , # of entries = 37888

57.8134% full, average # of collisions = 1.7835.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	184	106	127	134	120	99	53	47	27	24	103

Total collisions = 72699 , # of entries = 38912

59.3759% full, average # of collisions = 1.8683.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	149	101	124	143	134	96	73	37	37	20	110

Total collisions = 78514 , # of entries = 39936

60.9384% full, average # of collisions = 1.9660.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	121	80	126	128	125	112	73	52	43	31	133

Maximum collisions = 405

Total collisions = 84915 , # of entries = 40960

62.5010% full, average # of collisions = 2.0731.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	102	91	121	135	132	95	67	52	40	37	152

Total collisions = 91756 , # of entries = 41984

64.0635% full, average # of collisions = 2.1855.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	99	56	112	150	136	98	86	49	34	30	174

Total collisions = 99574 , # of entries = 43008

65.6260% full, average # of collisions = 2.3152.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	94	63	85	107	108	109	86	72	48	33	219

Total collisions = 108659 , # of entries = 44032

67.1885% full, average # of collisions = 2.4677.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	22	32	63	147	140	124	90	67	54	56	229

Total collisions = 116896 , # of entries = 45056

68.7511% full, average # of collisions = 2.5945.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	124	84	89	77	117	99	69	64	43	35	223

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Total collisions = 125384 , # of entries = 46080

70.3136% full, average # of collisions = 2.7210.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	61	52	70	109	126	89	89	71	58	50	249

Total collisions = 134434 , # of entries = 47104

71.8761% full, average # of collisions = 2.8540.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	98	65	66	81	100	88	91	71	57	55	252

Maximum collisions = 414

Total collisions = 146360 , # of entries = 48128

73.4386% full, average # of collisions = 3.0411.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	46	37	41	56	92	112	81	78	61	61	359

Maximum collisions = 474

Total collisions = 158022 , # of entries = 49152

75.0011% full, average # of collisions = 3.2150.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	34	44	58	91	102	107	94	74	61	42	317

Maximum collisions = 1114

Total collisions = 169432 , # of entries = 50176

76.5637% full, average # of collisions = 3.3768.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	66	65	71	92	97	87	89	70	68	56	263

Total collisions = 184332 , # of entries = 51200

78.1262% full, average # of collisions = 3.6002.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	39	28	29	36	78	68	79	84	61	57	465

Total collisions = 195029 , # of entries = 52224

79.6887% full, average # of collisions = 3.7345.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	40	56	45	78	87	100	90	97	70	47	314

Total collisions = 210482 , # of entries = 53248

81.2512% full, average # of collisions = 3.9529.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	28	15	37	47	62	65	83	80	75	59	473

Total collisions = 225298 , # of entries = 54272

82.8138% full, average # of collisions = 4.1513.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	55	48	54	51	59	63	58	80	77	63	416

Total collisions = 238403 , # of entries = 55296

84.3763% full, average # of collisions = 4.3114.

Collision density -->	0	1	2	3	4	5	6	7	8	9	10+
	43	46	48	53	62	74	70	60	71	71	426

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Total collisions = 251929 , # of entries = 56320  
 85.9388% full, average # of collisions = 4.4732.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           46 53 47 59 65 39 79 73 61 55 447  
 Maximum collisions = 4122

Total collisions = 272431 , # of entries = 57344  
 87.5013% full, average # of collisions = 4.7508.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           45 62 35 41 47 47 46 48 63 53 537

Total collisions = 293675 , # of entries = 58368  
 89.0639% full, average # of collisions = 5.0314.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           21 18 20 34 39 44 47 58 40 67 636

Total collisions = 318086 , # of entries = 59392  
 90.6264% full, average # of collisions = 5.3557.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           20 10 14 12 20 35 44 60 37 49 723

Total collisions = 344455 , # of entries = 60416  
 92.1889% full, average # of collisions = 5.7014.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           29 13 22 19 24 22 23 37 45 44 746

Total collisions = 373176 , # of entries = 61440  
 93.7514% full, average # of collisions = 6.0738.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           17 19 20 21 17 22 28 36 35 48 761  
 Maximum collisions = 10021

Total collisions = 406805 , # of entries = 62464  
 95.3140% full, average # of collisions = 6.5126.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           14 14 11 23 16 30 31 27 28 43 787

Total collisions = 464504 , # of entries = 63488  
 96.8765% full, average # of collisions = 7.3164.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           2 8 7 10 12 18 26 17 26 34 864

Total collisions = 529266 , # of entries = 64512  
 98.4390% full, average # of collisions = 8.2041.  
 Collision density --> 0 1 2 3 4 5 6 7 8 9 10+  
                           0 2 2 3 6 12 7 10 14 13 955

Program completed normally.

## CONCLUSION

Given more time I would actually implement the device into the proposed system for testing and evaluation. Simulation shows that at high table densities the average number of collisions is still small. Therefore, even as slow as the chip is now, we can expect fairly good results from it.

On the next pass the "known bugs" would be fixed and the layout would be done in CMOS to improve the speed of the device. As stated, the maximum speed at which the device simulates before failure is 2.5 Mhz. If that could be improved to a speed of say 50Mhz or 100Mhz, then the hash processor would have an apparent cycle time of one CPU cycle or less at lower table densities. At higher table densities the device will take longer to function.

The following paragraphs describe a host system configuration that the hash processor can be placed into for testing and evaluation.

System application for HTIC

The overall system shown in Figure 7 on page 60 describes a possible system configuration. The PC is used as a terminal to drive the 8086  $\mu$ P. Data is transferred over a serial interface to an ACIA (Asynchronous Communication Interface Adaptor) on board the  $\mu$ P system. The  $\mu$ P system is shown in Figure 8 on page 61. The HTIC is memory mapped to location A020 - A023 hex. Hence, the host CPU uses the HTIC as a coprocessor and the instructions to use the device are memory mapped reads and writes. There is some additional code that must be used in order to interpret the return codes of the HTIC. A complete memory map of the system is shown in Figure 9 on page 62

The following is a sequence of these samples entered from the terminal. However, these "calls" can come from a compiler or an assembler in the same way when the program needs data relating to a key. The instruction set for the CPU is find\_key(KEY) and write\_key(KEY). The find\_key() instruction calls a small assembler macro which will return the value of S0 and S1 to an internal register by doing a load accumulator from memory after the CPU has received an interrupt. The following cases are examples of how the system should operate.

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1. VAR1 = 10: This case will write a new value into the hash table. Assume that the table is initially empty and this is the first request to place data in the table.
2. VAR1 = 7: This case will overwrite the value of 10 that was written in case 1.
3. VAR1 = 7: This case will retrieve an existing value from the table. The value that will be returned is 7 because case 2 replaced the first value of 10.
4. VAR2 = 7: This case will return with a status of not found in the table. This is because the key "VAR2" has not been written to the table yet.

In the first case let us assume that the system has just been initialized and the table is completely empty. We first call find\_key(VAR1). This macro performs two writes to the HTIC. The first write is "VA" to KMR1 and the second write is "R1" to KMR2. Once the KMR2 has been written, the HTIC will execute the hash function on the key and begin its search into the table. Since the table is empty, the first location that the HTIC probes will interrupt the  $\mu P$  and return a status of "Location Empty". At this time the write\_key(VAR1) macro is called and the data value associated with VAR1 can be written into the hash table's



memory. The `write_key()` macro will then select the HTIC with L0 and L1 at logical 1's, thereby telling the HTIC to write the key into the hash table. On the next clock cycle, the  $\mu$ P will place the data portion, in this case 10, on its data bus. This will be written into the data table at the same time the HTIC is writing the most significant byte, VA, into the hash table. The  $\mu$ P will then wait for an interrupt from the HTIC while it is writing the least significant byte into the hash table. After the HTIC has finished writing to the data table, it will send an interrupt to the processor and wait to process the next request.

The second case will overwrite an existing value. In this case, the value 10 in location `f(VAR1)` will be overwritten. The HTIC will be loaded in the same format as case 1 and execute the hash function. However, this time the HTIC will return a status of "Found" on the first probe and the host CPU will read the value from the data table latch. The LOS will determine that the value read from the table is different from the value passed to the  $\mu$ P from the user and the new value will be written into the data table. The host CPU will assume that the user wants to do a variable update. A message of "OK, VAR1 UPDATED." will be returned to the terminal.

In the third case, the system will retrieve an already

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existing value from the data table. The LOS will interpret the question mark as a read only operation and attempt to find the specified key value in the hash table. Since we know that VAR1 already exists in the table, the HTIC will find the key in the table and interrupt the  $\mu P$  in the same way as in the previous case. However, since the LOS knows that this is a read only operation the system will read the data latch and return value found for the data location probed. A message of "VAR1 = 07" will be returned to the terminal.

The fourth case will try to read a value from the data table when there is no entry in the key table for the data. The HTIC will be loaded with the data and allowed to function. It will rehash until the binary counter overflows and interrupts the  $\mu P$ . At this point the status lines will contain "Not Found" and the  $\mu P$  will reset the PLA to state zero to break out of the rehash loop. Since the reset is a state only reset, the contents of all internal registers are preserved whenever the reset line is activated.

### Configuration Diagrams

# Hash Table Processor A Thesis

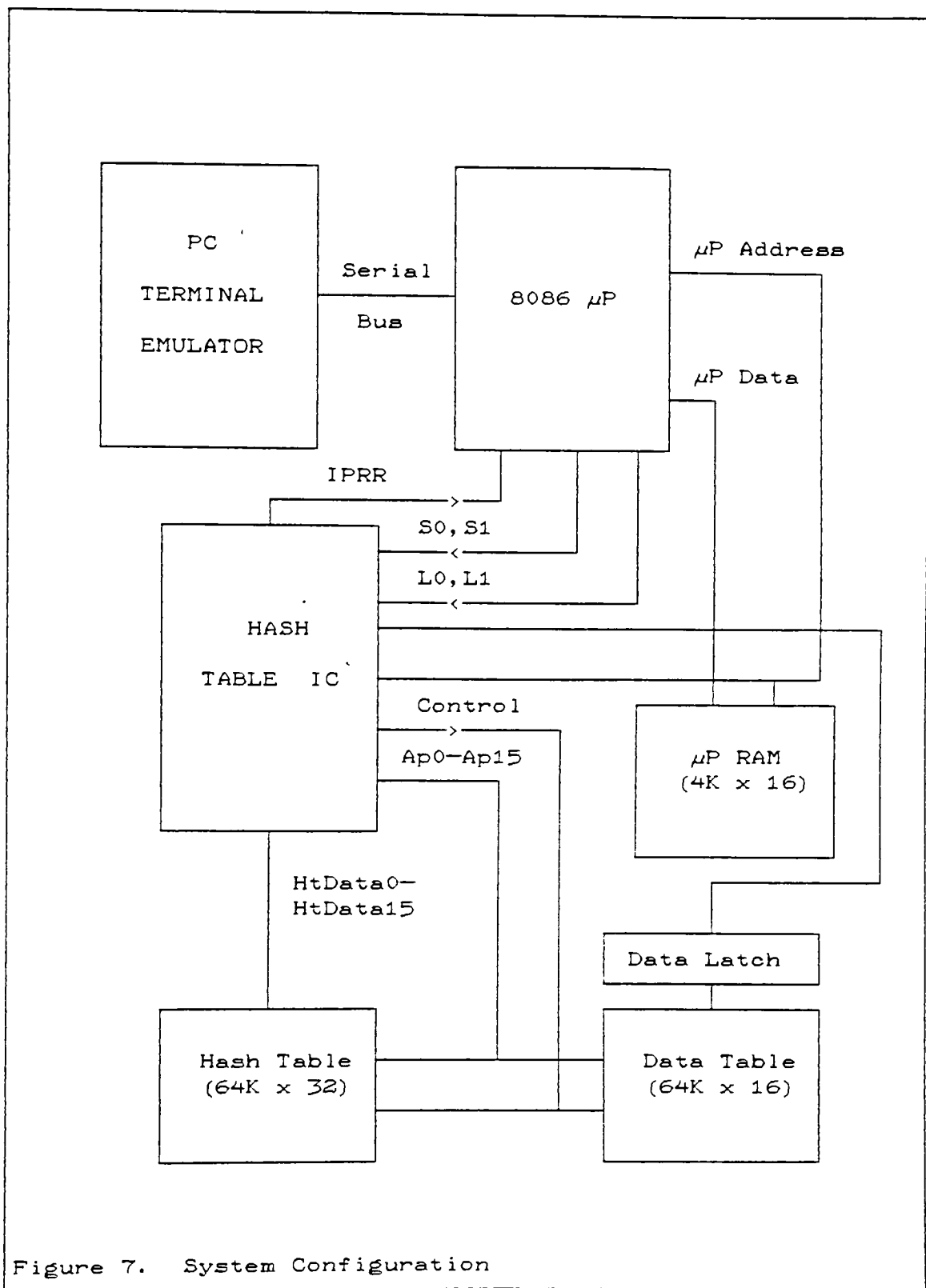
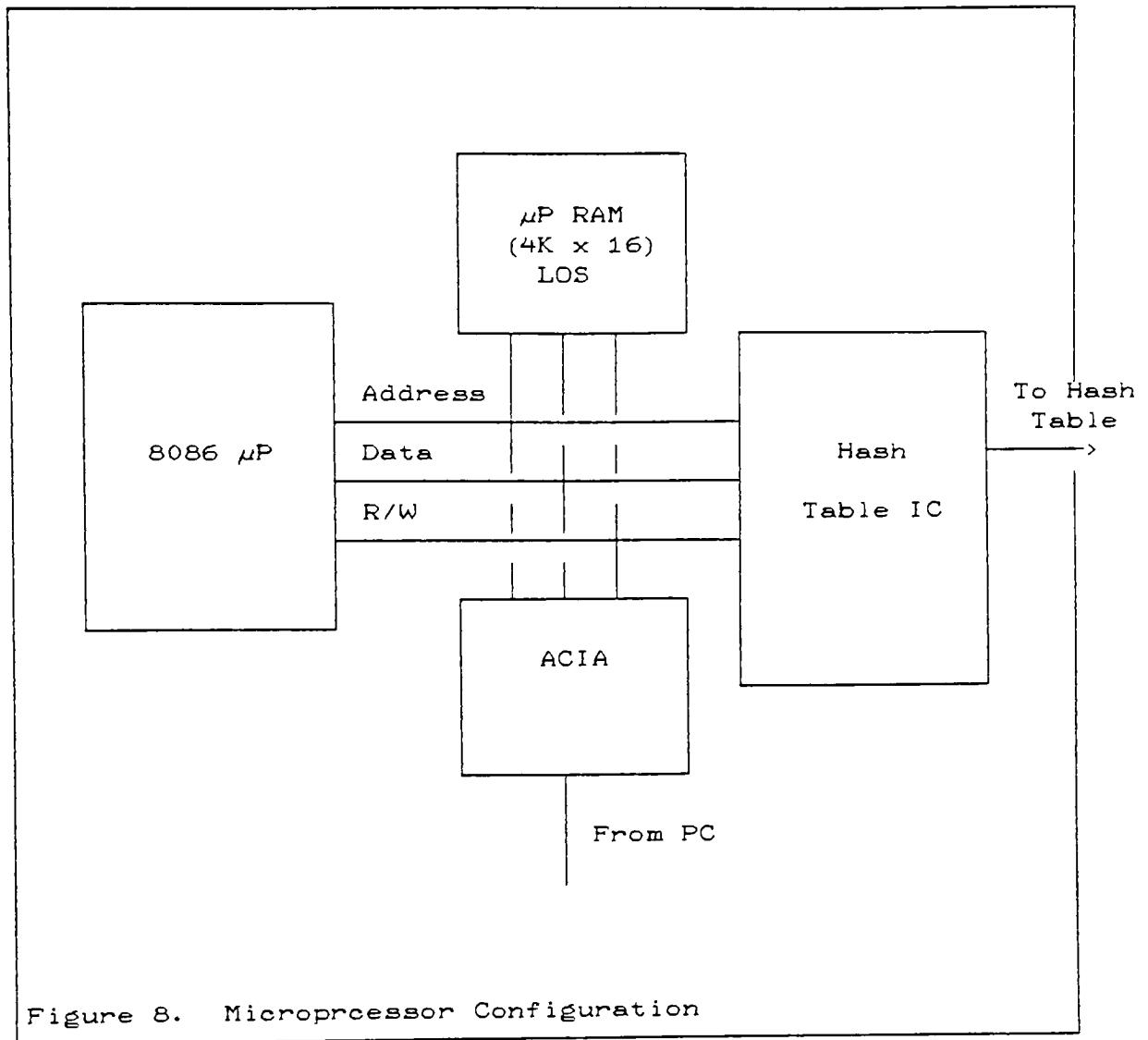


Figure 7. System Configuration

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Device	Address Range
LOS RAM	0000h 3FFFh
ACIA	A000h A003h
HASH IC	A020h A023h
DATA TABLE LATCH (Read) (Write)	A024h A025h

Figure 9. Microprocessor Memory Map

Software Design Specifications

The following sections define the specifications of the LOS that needs to reside in the microprocessor and the terminal emulation program that needs to reside in the PC.

### Terminal Emulator Program Specifications

The terminal emulation program will handle the communications between the microprocessor and the PC. The terminal emulator will send the  $\mu P$  a data packet consisting of the four characters in the key and the two bytes of data. If all four characters are not specified, then the emulator program will append the appropriate number of blanks. The equal sign is implied and it is not necessary to send it to the  $\mu P$  system.

### Local Operation System Specifications

The LOS has been broken into the following basic functions.

- To accept and receive data from the terminal.
- To interpret the data that has been sent and program the HTIC accordingly.
- To handle the interrupts that are sourced by the HTIC and process the data accordingly.
- Once the data has been processed, return status and data to the terminal emulation program.

GLOSSARY OF TERMS AND ACRONYMS

**VLSI** Very Large Scale Integration

**IC** Integrated Circuit

**CPU** Central Processing Unit. This is the main processing element in a computer system. This term will be used interchangeably with [P]. (See Below for [P])

**PLA** Programable Logic Array. A electronic circuit that controls the functionality of the HTIC. Also known as a state machine.

**KMR1** Key Memory Register #1. This register holds the first two characters of the variable name being processed.

**KMR2** Key Memory Register #2

**DREG** Delta Register

**EREG** Empty Register

**HREG** Hash Register

**ALU** Arithmetic Logic Unit

**$\mu$ P** Microprocessor

**ASCII** American Standard Code for Information Interchange.

**PIA** Peripheral Interface Adaptor

**ACIA** Asynchronous Communications Interface Adaptor. This device is used to send and receive data over a serial transmission line. The CPU will select this chip and pass it data 8 bits at a time. The ACIA will send this data out over its transmission line one bit at a time. The ACIA also adds extra information to each datum transmitted - start bits, stop bits and parity. All this extra information is user programmable from the CPU.

**RAM** Random Access Memory. This is where the CPU stores the instructions and data for operation. This memory can be written to or read from.

**4K** This term K is often used to denote 1024 bits or words. Therefore, 4K is 4 x 1024 or 4096 words.

**LOS** Local Operation System. This is a term used to

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describe a set of instructions that the CPU executes while the system is in use.

*DIP* Dual Inline Package

*NMOS* N-type Metal Oxide Semiconductor

*CMOS* Complementary Metal Oxide Semiconductor

*HTIC* Hash Table Integrated Circuit



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- Searching and sorting, The Art of computer programming Vol. 3, Addison Wesley Publishing Co. 1973, By Donald E. Knuth
- Operational characteristics of a hardware-based pattern matcher , By Rodger L. Haskin and Lee. A. Hollar.

APPENDIX A: SOURCE CODE TO GENERATE THE PLA.

```

PLA Hash_IC_Controller;
VAR
    Reset, L0, L1, R_W, CS1, CS2, CS3, Equal, Cout15 : CLOCKED_INPUT;
    s: ARRAY [0..4] OF STATE;
    HtData, CPUDData, Load, CKMR1, LKMR1, CKMR2, LKMR2,
    CEMpty, LEMpty, LHash, LDelta, Right, Left, Add,
    LResult, S0, S1, PadOut, HW, Write_Hash, EHT, IPRR : CLOCKED_OUTPUT;
    INORDER Reset, L0, L1, R_W, CS1, CS2, CS3, Equal, Cout15, s;
    OUTORDER s, S0, S1, HW, Write_Hash, EHT, IPRR, LResult, Add, Right, Left,
        LDelta, LHash, LEMpty, CEMpty, LKMR2, CKMR2, LKMR1,
        CKMR1, Load, CPUDData, HtData, PadOut;

BEGIN
    IF ~Reset THEN
    BEGIN
        CASE
            s = 0 :
                BEGIN
                    IF ~( ~CS1 and CS2 and CS3 ) THEN
                        BEGIN
                            Write_Hash := 1;
                            IPRR := 1; { Keep interrupt line high }
                            s := 0;
                        END;
                    IF ~CS1 and CS2 and CS3 THEN
                        BEGIN { This state will determine the proper action }
                            , { to take according to the user inputs L0 & L1 }
                            IF ~L0 and ~L1 and ~R_W THEN
                                BEGIN
                                    Write_Hash := 1;
                                    Load := 1;
                                    LKMR1 := 1;
                                    CPUDData := 1;
                                    IPRR := 1;
                                    s := 0;
                                END;
                            IF ~L0 and L1 and ~R_W THEN
                                BEGIN
                                    Write_Hash := 1;
                                    Load := 1;
                                    LKMR2 := 1;
                                    CPUDData := 1;
                                    IPRR := 1;
                                    s := 4;
                                END;
                            IF L0 and ~L1 and ~R_W THEN
                                BEGIN
                                    Write_Hash := 1;
                                    Load := 1;
                                    LEMpty := 1;

```

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```

        CPUData := 1;
        IPRR := 1;
        s := 16;
    END;
    IF L0 and L1 and ~R_W THEN
        BEGIN
            Write_Hash := 1;
            IPRR := 1;
            s := 2;
        END;
    END { End the s0 'if statment }
    ELSE s := 0;
END; { End the entire s0 }
s = 1 :
    BEGIN
        Write_Hash := 1;
        IPRR := 1;
    END;
s = 2 :
    BEGIN
        { This state will write a new key into the table.}
        HW := 1;      { Enable the high word block of the hash table.  }
        Write_Hash := 0; { Write to Hash Table.                        }
        EHT := 1;     { data value associated with the new key.          }
        { Enable Hash Table (both Key and Data tables) }
        CKMR1 := 1;
        Load := 1;
        HtData := 1;
        PadOut := 1;
        IPRR := 1;
        s := 3;
    END;
s = 3 :
    BEGIN
        HW := 0;
        Write_Hash := 0; { Write to Hash Table. (This Is inverted  }
                        { before the output pad)                      }
        EHT := 1;
        CKMR2 := 1;
        Load := 1;
        HtData := 1;
        PadOut := 1;
        IPRR := 1;
        s := 0;
    END;
s = 4 :
    BEGIN
        { This state will load the initial hash into the }
        { lower 8 bits of hash register. (Ap0 - Ap7)      }
        Write_Hash := 1;
        CKMR1 := 1;
        LHash := 1;
        Right := 1;
        IPRR := 1;
        s := 5;
    END;

```

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```

END;
s = 5 :
BEGIN      { This state will load the initial hash into the }
           { upper 8 bits of hash register. (Ap8 - Ap15)      }
  Write_Hash := 1;
  CKMR2 := 1;
  LHash := 1;
  Left := 1;
  IPRR := 1;
  s := 6;
END;
s = 6 :
BEGIN      { This state will load the initial hash into the }
           { lower 8 bits of delta register.                  }
  Write_Hash := 1;
  CKMR1 := 1;
  LDelta := 1;
  Right := 1;
  IPRR := 1;
  s := 7;
END;
s = 7 :
BEGIN      { This state will load the initial hash into the }
           { upper 8 bits of delta register.                  }
  Write_Hash := 1;
  CKMR2 := 1;
  LDelta := 1;
  Left := 1;
  IPRR := 1;
  s := 8;
END;
s = 8 :
BEGIN
  CKMR1 := 1;      { Set up test for next cycle }
  HtData := 1;
  HW := 1;
  EHT := 1;
  IPRR := 1;
  Write_Hash := 1;
  s := 9;
END;
s = 9 :
BEGIN
  IF Equal THEN
    BEGIN
      CKMR2 := 1;      { Set up for next test, KMR2 := KEY }
      HtData := 1;     { Access the Hash Table data }
      HW := 0;         { Set low word of hash table active }
      EHT := 1;        { Enable Hash Table }
      IPRR := 1;
      Write_Hash := 1; { Read from hash table }
      s := 10;         { STATUS : KMR1 Equal, try KMR2 }
    END;
  END;

```

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```

IF ~Equal THEN
    BEGIN
        CEmpty := 1;
        HtData := 1;
        HW := 1;
        EHT := 1;
        IPRR := 1;
        Write_Hash := 1; { Read from hash table }
        s := 11; { STATUS : KMR1 Not Equal, try empty }
    END;
END;

s = 10 :
BEGIN
    IF Equal THEN
        BEGIN
            IPRR := 1;
            Write_Hash := 1;
            s := 14; { STATUS : Found }
        END;
    IF ~Equal THEN
        BEGIN
            CEmpty := 1; { Set up for test on next cycle }
            HtData := 1;
            HW := 0;
            Write_Hash := 1; { Read from hash table }
            EHT := 1;
            IPRR := 1;
            s := 11; { STATUS : Not Equal, try Empty }
        END;
    END;
END;

s = 11 :
BEGIN
    IF Equal THEN
        BEGIN
            Write_Hash := 1;
            IPRR := 1;
            s := 15 { STATUS : Location Empty }
        END;
    IF ~Equal THEN
        BEGIN
            Write_Hash := 1;
            IPRR := 1;
            s := 12; { STATUS : Not Empty and Not Equal }
        END;
        { goto rehash. }
    END;
END;

s = 12 :
BEGIN
    Write_Hash := 1;
    Add := 1; { Compute the next hash }
    IPRR := 1;
    s := 13;
END;

s = 13 :

```

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BEGIN
  Write_Hash := 1;
  LResult := 1; { Load Result and re-probe table }
  IPRR := 1;
  s := 8;
END;
s = 14 :
BEGIN
  Write_Hash := 1;
  IPRR := 0; { Send Interrupt to Precessor, Result Ready }
  S0 := 0; { RETURN STATUS : 0 1 (Found Key) }
  S1 := 1;
  s := 0; { Go wait for more input }
END;
s = 15 :
BEGIN
  Write_Hash := 1;
  IPRR := 0; { Send Interrupt to Precessor, Result Ready }
  S0 := 1; { RETURN STATUS : 1 0 (Location Empty) }
  S1 := 0;
  s := 0; { Go wait for more input }
END;
s = 16 :
BEGIN
  Write_Hash := 1;
  CKMR1 := 1; { States 16 .. 19 will initialize the hash }
  LHash := 1; { and delta to equal 0. This will set up }
  Right := 1; { the chip to write the EMPTY KEY VALUE to }
  IPRR := 1; { all 64K memory locations. }
  s := 17;
END;
s = 17 :
BEGIN
  Write_Hash := 1;
  CKMR1 := 1;
  LHash := 1;
  Left := 1;
  IPRR := 1;
  s := 18;
END;
s = 18 :
BEGIN
  Write_Hash := 1;
  CKMR1 := 1;
  LDelta := 1;
  Right := 1;
  IPRR := 1;
  s := 19;
END;
s = 19 :
BEGIN
  Write_Hash := 1;
  CKMR1 := 1;

```

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```

    LDelta := 1;
    Left := 1;
    IPRR := 1;
    s := 20;
END;
s = 20 :
BEGIN
    IPRR := 1;
    HW := 1;           { Enable the high word. }
    Write_Hash := 0;   { Enable Hash Write.   }
    EHT := 1;          { Enable Hash Table.   }
    PadOut := 1;       { Change pads to output. }
    Load := 1;
    HtData := 1;       { Enable the data pads }
    CEmpty := 1;       { Write the contents of the empty }
    s := 21;           { register into memory.   }
END;
s = 21 :
BEGIN
    IPRR := 1;
    HW := 0;           { Enable the low word. }
    Write_Hash := 0;   { Enable Hash Write.   }
    EHT := 1;          { Enable Hash Table.   }
    PadOut := 1;       { Change pads to output. }
    Load := 1;
    HtData := 1;       { Enable the data pads }
    CEmpty := 1;       { Write contents into memory. }
    s := 22;
END;
s = 22 :
BEGIN
    Write_Hash := 1;
    Add := 1;          { Increment address pionter by 1 }
    IPRR := 1;         { AP := Cin1 + Hash + Delta   }
    s := 23;           { Cin = 1; Delta = 0; -->   }
END;
{ AP := Hash + 1 to get incrmenter }
s = 23 :
BEGIN
    Write_Hash := 1;
    LResult := 1;      { Capture Result of addition }
    IPRR := 1;
    s := 24;
END;
s = 24 :
BEGIN
    IF Cout15 THEN
        BEGIN
            Write_Hash := 1;
            IPRR := 0;   { Send interrupt to CPU }
            s := 0;      { Go wait for input.   }
        END;
    IF ~Cout15 THEN
        BEGIN

```

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```
        Write_Hash := 1;
        IPRR := 1;      { Not done, do not interrupt }
        s := 20;        { Go write next location.      }
    END;

    END;
END; (* CASE *)
END
END.
```



APPENDIX B: SOURCE CODE FOR HASH FUNCTION SIMULATION.

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```

/*****
/*
/*          Include the following files :
/*
/*
/*****
#include <c:\include\stdio.h>
#include <c:\include\math.h>
#include <c:\include\ctype.h>
#include <c:\include\malloc.h>
#include <c:\include\string.h>
/*****
/*
/*          Decloration of constants used in the program.
/*
/*
/*****
#define TABLE_SIZE      65535
#define KEY_SIZE          4
#define BIT_MASK          1
#define HASH_MASK         0x0000FFFF
#define MASK_0001          0x0001
#define MASK_0002          0x0002
#define MASK_0004          0x0004
#define MASK_0008          0x0008
#define MASK_0010          0x0010
#define MASK_0020          0x0020
#define MASK_0040          0x0040
#define MASK_0080          0x0080
#define MASK_0100          0x0100
#define MASK_0200          0x0200
#define MASK_0400          0x0400
#define MASK_0800          0x0800
#define MASK_1000          0x1000
#define MASK_2000          0x2000
#define MASK_4000          0x4000
#define MASK_8000          0x8000

```

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PAGE 1  
03-20-88  
21:50:13

```
Line# Source Line Microsoft C Compiler Version 5.00
1      /* Program Name : Hash
2      * Written By : Robert P. Ketrick
3      * Program Description :
4
5      This program is submitted in partial fulfillment of the requirements
6      stated in the Hash Memory IC Thesis proposal. The intent of this code
7      is to gather statistical information on the hashing function used in
8      the integrated circuit designed in this thesis.
9      The data for this program is generated from "gendata.c" which will
10     generate random strings of four (4) characters that are used as keys.
11     This program will take those keys as input and attempt to find a place
12     in the hash table for each key until the table exceeds 98% full.
13
14     In the first case the entry is thrown out of the sample and another
15     key is read. In the second case the program will terminate.
16     */
17
18     #include "hash.h"
19
20     /* These are the global variables to be used in the hash program */
21
22     unsigned char key[KEY_SIZE];
23     char table[TABLE_SIZE][4] , empty_string[4] ;
24     long int hash, delta ;
25
26     main(argc, argv)
27     int argc;
28     char *argv[];
29     {
30
31     /* These are the local variables to be used in the hash program */
32
33     FILE *in, *out, *fopen();
34     int collision = 0, finished = 0 , count = 0;
35     int max_collisions = 0 ;
36     long int i ;
37     register j ;
38     unsigned long int entries = 0 ;
39     unsigned long int total_collisions = 0 ;
40     float average_hit = 0.0, percent_full = 0.0 ;
41     char *newkey ;
42
43     int coll_00 = 0, /* These ints track the collision density */
44     coll_01 = 0, /* of the hash function. */
45     coll_02 = 0,
46     coll_03 = 0,
47     coll_04 = 0,
48     coll_05 = 0,
49     coll_06 = 0,
```

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```

50         coll_07 = 0,
51         coll_08 = 0,
52         coll_09 = 0,
53         coll_10 = 0;
54
55
56     if (argc == 1)    {
57
58         /* no args; print error and exit */
59
60         fprintf(stderr, "hash: must have file as input.\n\n");
61         fprintf(stderr, "usage : hash <infile> \n");
62
63     } else {
64
65         /* get the data file for processing */
66
67         if ((in = fopen(++argv, "r")) == NULL) {
68             fprintf(stderr, "hash: can't open %s\n", *argv);
69             exit(1);
70
71         } /* endif fopen() */
72
73     } /* endif argc == 1 */
74
75     fprintf(stdout, "Initializing table, please wait .... ");
76
77
78     /*****
79     /*
80     /* The table is initialized to all '****' to show that the
81     /* table is empty.
82     /*
83     /*****
84
85     for (i = 0; i <= TABLE_SIZE ; i++)
86         for ( j  = 0; j < 4; j++) table[i][j] = '*';
87
88     for ( i = 0; i < 4; i++) empty_string[i] = '*';
89
90     fprintf(stdout, "Done. \n");
91
92     while ((fread(key, 5, 1, in) > 0) &&
93           (entries < (TABLE_SIZE - 1020))) {
94
95         finished = collision = 0;
96         key[4] = '\0';
97         hashkey(key);
98
99         while ( finished == 0 ) {
100
101
102     /*****

```

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```

103      /*
104      /* Since we are only looking for statistacal information on
105      /* the performance of the hash function we will discard but
106      /* notify when we encounter duplicate entries in the table.
107      /*
108      /******
109
110          if ((j = comp(key)) == 1) {
111
112              finished = 1 ;
113              fprintf(stdout,
114                  "Duplicate entries in table for %s. \n",key);
115
116          } /* endif */
117
118
119      /******
120      /*
121      /* If the pointer in the table points to a "empty_string"
122      /* then add one to the number of entries in the table and
123      /* allocate the space and copy the new "key" string into the
124      /* table.
125      /*
126      /******
127
128          if ((j = comp(empty_string)) == 1) {
129
130              for (i = 0 ; i < 4; i++) table[hash][i] = key[i]
131              entries ++ ;
132              count ++ ;
133              finished = 1 ;
134
135      /******
136      /*
137      /* Keep track of the collision density per 1K table entries.
138      /*
139      /******
140
141          switch (collision) {
142              case 0 :
143                  coll_00 ++ ;
144                  break;
145              case 1 :
146                  coll_01 ++ ;
147                  break;
148              case 2 :
149                  coll_02 ++ ;
150                  break;
151              case 3 :
152                  coll_03 ++ ;
153                  break;
154              case 4 :
155                  coll_04 ++ ;

```

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```

156         break;
157     case 5 :
158         coll_05 ++ ;
159         break;
160     case 6 :
161         coll_06 ++ ;
162         break;
163     case 7 :
164         coll_07 ++ ;
165         break;
166     case 8 :
167         coll_08 ++ ;
168         break;
169     case 9 :
170         coll_09 ++ ;
171         break;
172     default:
173         coll_10 ++ ;
174         break;
175     } /* endswitch */
176
177     } /* endif for strcmp() */
178
179     /***/
180     /*
181     /* This section will perform the re-hash function and record
182     /* that a collision has taken place. Also, if the number of
183     /* collisions exceed 100 then the entry is thrown out of the
184     /* sample.
185     /*
186     /***/
187
188     if ((j = comp(key)) == 0) {
189
190         /* Re-hash function for the chip */
191
192         hash = (hash + delta + 1) & HASH_MASK ;
193
194         collision++ ;
195         finished = 0 ;
196
197         if (collision > max_collisions) {
198
199             max_collisions = collision ;
200             fprintf(stdout, "Maximum collisions = %d \n",
201                     collision);
202         }
203
204     } /* end comp */
205
206     } /* endwhile not finished */
207
208

```

```
total_collisions += collision ;
```

Appendix B: Source code for hash function simulation.

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```
255     } /* endwhile fread */
256
257     fprintf(stdout, "\nProgram completed normally.\n");
258
259 } /* end of main program */
260
261 hashkey(newkey)
262 char *newkey ;
263 {
264     register int l,m ;
265     int index ;
266     unsigned char temp ;
267
268
269     /*****
270     /*
271     /* Assign the ASCII characters to there corresponding integer
272     /* values by converting then to type int.
273     /*
274     /*****/
275
276     hash = 0;
277     delta = 0;
278
279     for (l = 0; l < 4; l++){
280
281         temp = newkey[l] ;
282         index = 8 * l ;
283
284         for (m = 0 ; m < 8 ; m++) {
285
286             if ((temp & BIT_MASK) == 1) setbit(m+index) ;
287             temp >>= 1;
288
289         } /* endfor */
290
291     } /* endfor */
292
293 }
294 setbit(x)
295 int x;
296 {
297
298     switch (x) {
299
300         case 0 :
301             delta := MASK_8000 ;
302             break;
303
304         case 1 :
305             hash := MASK_8000 ;
306             break;
307     }
```



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```
308      case 2 :
309          delta := MASK_4000 ;
310          break;
311
312      case 3 :
313          hash := MASK_4000 ;
314          break;
315
316      case 4 :
317          delta := MASK_2000 ;
318          break;
319
320      case 5 :
321          hash := MASK_2000 ;
322          break;
323
324      case 6 :
325          delta := MASK_1000 ;
326          break;
327
328      case 7 :
329          hash := MASK_1000 ;
330          break;
331
332      case 8 :
333          delta := MASK_0800 ;
334          break;
335
336      case 9 :
337          hash := MASK_0800 ;
338          break;
339
340      case 10 :
341          delta := MASK_0400 ;
342          break;
343
344      case 11 :
345          hash := MASK_0400 ;
346          break;
347
348      case 12 :
349          delta := MASK_0200 ;
350          break;
351
352      case 13 :
353          hash := MASK_0200 ;
354          break;
355
356      case 14 :
357          delta := MASK_0100 ;
358          break;
359
360      case 15 :
```

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```
361         hash |= MASK_0100 ;
362         break;
363
364     case 16 :
365         delta |= MASK_0080 ;
366         break;
367
368     case 17 :
369         hash |= MASK_0080 ;
370         break;
371
372     case 18 :
373         delta |= MASK_0040 ;
374         break;
375
376     case 19 :
377         hash |= MASK_0040 ;
378         break;
379
380     case 20 :
381         delta |= MASK_0020 ;
382         break;
383
384     case 21 :
385         hash |= MASK_0020 ;
386         break;
387
388     case 22 :
389         delta |= MASK_0010 ;
390         break;
391
392     case 23 :
393         hash |= MASK_0010 ;
394         break;
395
396     case 24 :
397         delta |= MASK_0008 ;
398         break;
399
400     case 25 :
401         hash |= MASK_0008 ;
402         break;
403
404     case 26 :
405         delta |= MASK_0004 ;
406         break;
407
408     case 27 :
409         hash |= MASK_0004 ;
410         break;
411
412     case 28 :
413         delta |= MASK_0002 ;
```

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```
414         break;
415
416     case 29 :
417         hash != MASK_0002 ;
418         break;
419
420     case 30 :
421         delta != MASK_0001 ;
422         break;
423
424     case 31 :
425         hash != MASK_0001 ;
426         break;
427
428     default:
429         err_badbit();
430         break;
431
432     } /* endswitch */
433
434 }
435 comp(buff)
436 char buff[];
437 {
438     int equal ;
439     register i = 0 ;
440
441     while ((table[hash][i] == buff[i]) && (i < 4)) { i++ ; }
442     if (i == 4 ) return(1); else return(0);
443 }
444 err_badbit()
445 {
446     fprintf(stderr,
447         "A bad bit was attempted to be set in routine setbit.\n");
448     fprintf(stderr, "Program aborted. \n");
449     exit(10);
450 }
```

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21:50:13

Microsoft C Compiler Version 5.00

No errors detected

APPENDIX C: SOURCE CODE FOR GENERATING TEST DATA.

PAGE 1

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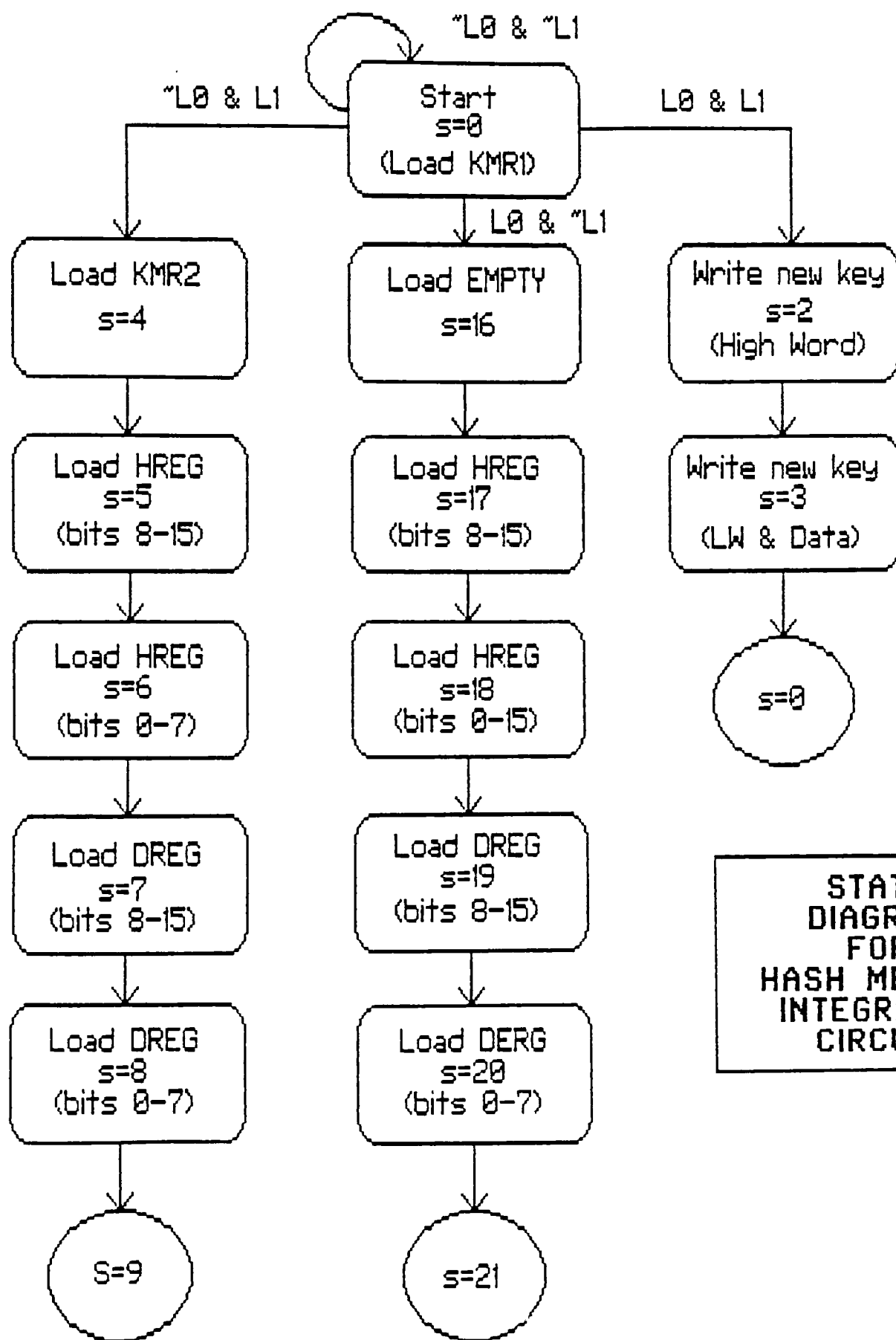
15:09:40

```
Line# Source Line IBM Personal Computer C Compiler Version 5.00
1      /* Program Name : GENDATA
2      * Written By : Bob Ketrick
3      * Program Description : This program generates strings of
4      * printable ASCII characters that are used as input to the
5      * hash table processor simulation program. The program will
6      */ generate TABLE_SIZE number keys.
7
8      #include "c:\ibm\include\stdio.h"
9      #include "c:\ibm\include\stdlib.h"
10     #include "c:\ibm\include\string.h"
11
12     #define TABLE_SIZE 70000
13
14
15     main(argc, argv)
16     int argc;
17     char *argv[];
18     {
19
20     /* These are the local variables to be used in the hash program */
21
22     FILE *out, *fopen();
23     int rnd ;
24     char *key , *empty = "****\0" ;
25     unsigned long int count = 0 ;
26     register i = 0 ;
27
28     if (argc != 3) {
29
30     /* no args; print error and exit */
31
32     fprintf(stderr, "usage : gendata <outfile> <seed> \n");
33     exit(0);
34
35     } else {
36
37     /* get the data file for processing */
38
39     if ((out = fopen(argv[1] , "w")) == NULL) {
40     fprintf(stderr, "hash: can't open %s\n", *argv);
41     exit(1);
42
43     } /* endif fopen() */
44
45     } /* endif argc != 3 */
```

Hash Table Processor  
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```
46
47      srand(*argv[2] & '\x0F');
48      fprintf(stdout,"Seed value = %d \n\n",(*argv[2] & '\x0F'));
49
50      while ( count <= TABLE_SIZE ) {
51
52
53          rnd = rand() % 127 ;
54
55          if ((rnd >= '\x30') && (rnd <= '\x7D')) {
56
57              key[i++] = rnd ;
58
59              if (i == 4) {
60
61                  i = 0 ;
62                  if (strcmp(key,empty) != 0) {
63
64                      key[4] = '\0' ;
65                      fprintf(out,"%s\n",key);
66                      count++ ;
67                      if ((count >= 10000) &&
68                          ((count % 10000) == 0))
69                          fprintf(stdout,
70                              "%ld keys generated.\n",count);
71
72                      } /* endif */
73
74                      } /* endif */
75
76                  } /* endif */
77
78          } /* endwhile */
79
80 } /* end of main program */
No errors detected
```

APPENDIX D: STATE DIAGRAM FOR PLA.



STATE  
DIAGRAM  
FOR  
HASH MEMORY  
INTEGRATED  
CIRCUIT

